

Termination of Polynomial Programs

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A Simple Terminating Loop

Loop:

$$\tau_1 : \{x \geq y\} \rightarrow \{x' = x, y' = y + 1\}$$

Why does it terminate?

$x - y$ is a *ranking function*:

- $x - y$ is well-founded by $x \geq y$.
- $x - y$ decreases on each iteration:

$$\begin{aligned}(x - y)' - (x - y) &= x' - y' - x + y \\ &= x - y - 1 - x + y \\ &= -1\end{aligned}$$

A Simple Change, but not-so-simple Termination

Loop:

$$\tau_1 : \{x \geq y\} \rightarrow \{x' = x + 1, y' = y + x\}$$

Why does it terminate?

- $x - y$ is still well-founded by $x \geq y$.
- But $x - y$ does not decrease on each iteration (when $x \leq 0$).

Idea: Look at higher-order differences.

Termination by Higher-order Differences

- $x - y$ is well-founded by $x \geq y$.
- Decreasing?
 - First difference:

$$(x - y)' - (x - y) = 1 - x$$

x can be nonpositive, so not decreasing.

- Second difference:

$$(1 - x)' - (1 - x) = -1$$

So *eventually* only decreasing.

Multiple Paths

What about multiple paths in the loop? Example:

$$\tau_1 : \{x \geq y\} \rightarrow \{x' = x + 1, y' = y + x, z' = z\}$$

$$\tau_2 : \{x \geq y\} \rightarrow \{x' = x - z, y' = y + z^2, z' = z - 1\}$$

Does it terminate?

- $x - y$ is well-founded by $x \geq y$.
- τ_1 like before.
- In τ_2 , eventually y increases more quickly than x .
- But do they *interfere* with each other?

Interference

$$\tau_1 : \{x \geq 0\} \rightarrow \{x' = x + z, y' = y + 1, z' = z - 2\}$$

$$\tau_2 : \{x \geq 0\} \rightarrow \{x' = x + y, y' = y - 2, z' = z\}$$

Does it terminate?

- $y' = y + 1$ in τ_1 definitely interferes with $y' = y - 2$ in τ_2 .
- But each transition terminates by itself.

Related Work

- Synthesis of *linear ranking functions*
Colon & Sipma, 2001 : manipulation of polyhedral cones
Colon & Sipma, 2002 : practical applications
Podelski & Rybalchenko, 2004 : results for single path
- Nonlinear techniques
Tiwari, 2004 : simple linear loops decidable
- Functional programs (huge literature)
 - *Size-change principle*: **Lee, Jones, & Ben-Amram, 2001**, technique for analyzing function-call structure
- Finite differences in programs
 - construction and automatic solving of recurrence equations
 - invariants, running times, termination
 - **Cohen, 1982; Katz & Manna, 1976; Wegbreit, 1975**

The Two Main Ideas

Idea 1: *Examine higher-order differences.*

Idea 2: *Look at eventual trends.*

The rest of the talk:

- Finite difference trees and approximations
- Termination analysis
- Experimental results

Polynomial Programs

Structure:

- *initial condition*: conjunction of polynomial assertions
- set of *guarded commands*
 - *guard*: conjunction of polynomial assertions
 - *update*: simultaneous assignment of polynomial expressions to variables

Theorem: Termination of polynomial programs is not even semi-decidable.

Finite Difference Trees (FDT's)

Represent finite differences by tree:

- τ_i -child of a node with expression $E(\mathbf{x})$ is labeled with expression

$$E(\mathbf{x}') - E(\mathbf{x})$$

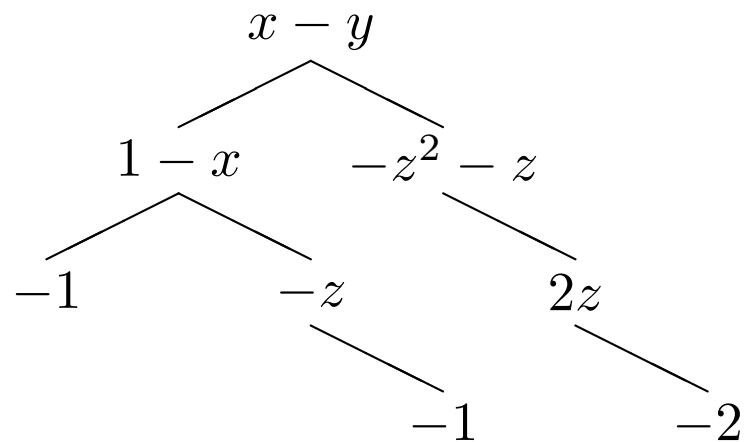
where τ_i determines \mathbf{x}' .

- *Leaves* are nodes with only 0-children.

Example

$$\tau_1 : \{x \geq y\} \rightarrow \{x' = x + 1, y' = y + x, z' = z\}$$

$$\tau_2 : \{x \geq y\} \rightarrow \{x' = x - z, y' = y + z^2, z' = z - 1\}$$



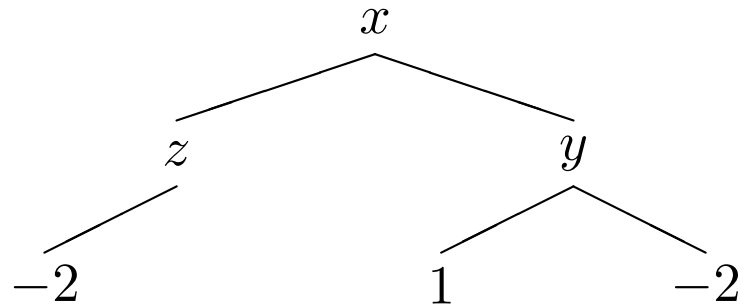
Remarks:

- τ_2 interferes with τ_1 , but eventually aids progress.
- τ_1 does not interfere with τ_2 .

Example

$$\tau_1 : \{x \geq 0\} \rightarrow \{x' = x + z, y' = y + 1, z' = z - 2\}$$

$$\tau_2 : \{x \geq 0\} \rightarrow \{x' = x + y, y' = y - 2, z' = z\}$$



Remarks:

- τ_1 negatively interferes with progress of τ_2 .
- But we can still prove termination.

Finite vs. Infinite FDT

- A finite FDT indicates *polynomial* behavior.
- An infinite FDT indicates *exponential* behavior.
- Can use invariants for both cases.

More on this later.

Approximation: Taylored FDT

Idea: Use Taylor series expansion for analysis. But $\frac{\partial^2 f}{\partial x \partial y} \neq \frac{\partial^2 f}{\partial y \partial x}$.

Definition: *Critical nodes* are nodes $\Delta_T E(\mathbf{x})$ such that for all permutations σ , $\Delta_{\sigma(T)} E(\mathbf{x})$ is a constant expression.

Approximation: Construct *Taylored FDT* so that:

- Each *critical node* $\Delta_T E(\mathbf{x})$ has value

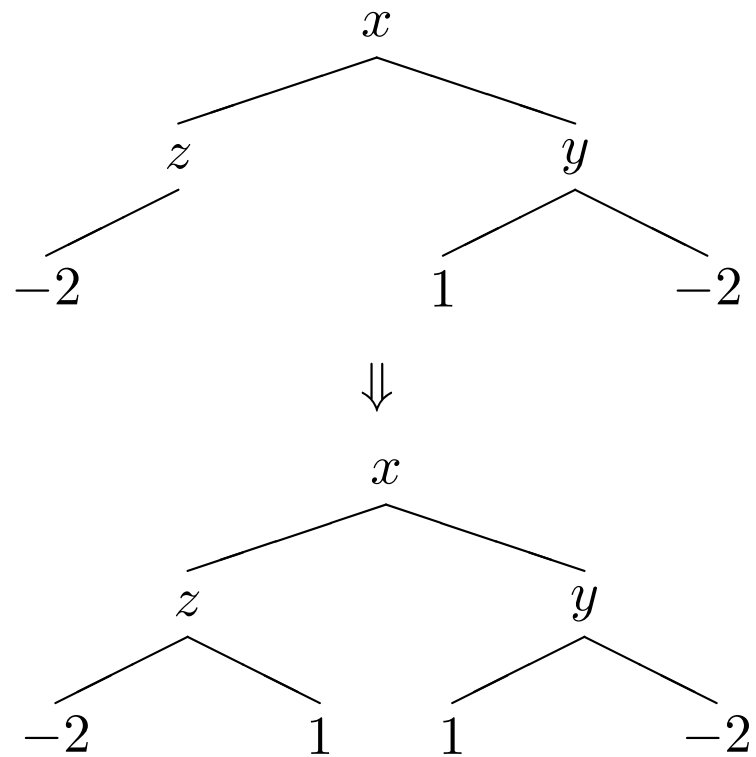
$$\max_{\sigma} \Delta_{\sigma(T)} E(\mathbf{x})$$

- All other nodes remain unchanged.

Example

$$\tau_1 : \{x \geq 0\} \rightarrow \{x' = x + z, y' = y + 1, z' = z - 2\}$$

$$\tau_2 : \{x \geq 0\} \rightarrow \{x' = x + y, y' = y - 2, z' = z\}$$



Analysis: Dominant Taylor Expression

Definition: *Dominant Taylor expression* (DTE) for a Taylored FDT:

$$\sum_{\Delta_T E(\mathbf{x}) \in \text{critical_nodes}(t)} \frac{\prod_{\tau \in T} x_{\tau}}{|T|!} \Delta_T E(\mathbf{x})$$

where

- T are viewed as lists or multisets,
- one variable x_{τ_i} introduced per transition τ_i .

Remarks:

- x_{τ_i} counts the number of times τ_i is taken.
- Dominant terms of full Taylor series expansion for specific computations. So, $\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}$ where it matters.

Analysis: Dominant Taylor Expression

Idea:

- Partition set of infinite computations by transitions that occur infinitely often.
- Show that $E(\mathbf{x})$ eventually only decreases in each set.

Form DTE for each nonempty subset $\mathcal{T}' \subseteq \mathcal{T}$.

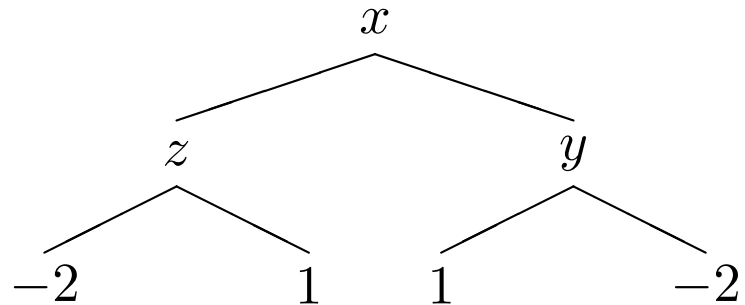
- Each \mathcal{T}' represents a set of infinite computations.
- Ensures that dominant terms really are dominant.

Proposition: If for each nonempty $\mathcal{T}' \subseteq \mathcal{T}$, the DTE of $E(\mathbf{x})$ with respect to \mathcal{T}' *eventually only decreases as the length of the computation increases*, then $E(\mathbf{x})$ eventually only decreases.

Example

$$\tau_1 : \{x \geq 0\} \rightarrow \{x' = x + z, y' = y + 1, z' = z - 2\}$$

$$\tau_2 : \{x \geq 0\} \rightarrow \{x' = x + y, y' = y - 2, z' = z\}$$



Dominant Taylor expressions:

- $\{\tau_1\} \subseteq \{\tau_1, \tau_2\}$: $-2 \cdot \frac{1}{2!} x_1^2 = -x_1^2 \Rightarrow \text{decreases}$
- $\{\tau_2\} \subseteq \{\tau_1, \tau_2\}$: $-2 \cdot \frac{1}{2!} x_2^2 = -x_2^2 \Rightarrow \text{decreases}$

Example

- $\{\tau_1, \tau_2\} \subseteq \{\tau_1, \tau_2\}$:

$$\begin{aligned} & -2 \cdot \frac{1}{2!} x_1^2 + \frac{1}{2!} x_1 x_2 + \frac{1}{2!} x_2 x_1 - 2 \cdot \frac{1}{2!} x_2^2 \\ &= -x_1^2 + x_1 x_2 - x_2^2 \\ &= -r^2 \cos^2 \theta + r^2 \cos \theta \sin \theta - r^2 \sin^2 \theta \\ & \quad \text{letting } x_1 = r \cos \theta, x_2 = r \sin \theta \\ &= r^2 (\cos \theta \sin \theta - 1) \\ &= Q(r, \theta) \end{aligned}$$

But

$$\frac{\partial Q}{\partial r} = 2r(\cos \theta \sin \theta - 1) \quad \text{and} \quad \frac{\partial^2 Q}{\partial r^2} = 2(\cos \theta \sin \theta - 1)$$

Over $\theta \in [0, \frac{\pi}{2}]$, maximum of $\frac{\partial^2 Q}{\partial r^2}$ is -1 . \Rightarrow *decreases*

Example

- For each nonempty $\mathcal{T}' \subseteq \{\tau_1, \tau_2\}$, x was shown eventually only to decrease w.r.t. \mathcal{T}' occurring i.o.
- Therefore, x eventually only decreases on all nonterminating computations.
- But x bounded from below by 0.
- So the loop terminates on all input.

Simple Analysis: Standard Condition

Definition: A τ_i -child is *decreasing* if

- its expression is at most some negative constant,
- or if its τ_i child is *decreasing* and its other children are decreasing or nonpositive.

Definition: A FDT meets the *standard condition* if for every τ_i , the root's τ_i -child is decreasing.

Simple Analysis: Standard Condition

Proposition: If the FDT of $E(\mathbf{x})$ with respect to \mathcal{T} meets the standard condition, then $E(\mathbf{x})$ eventually only decreases.

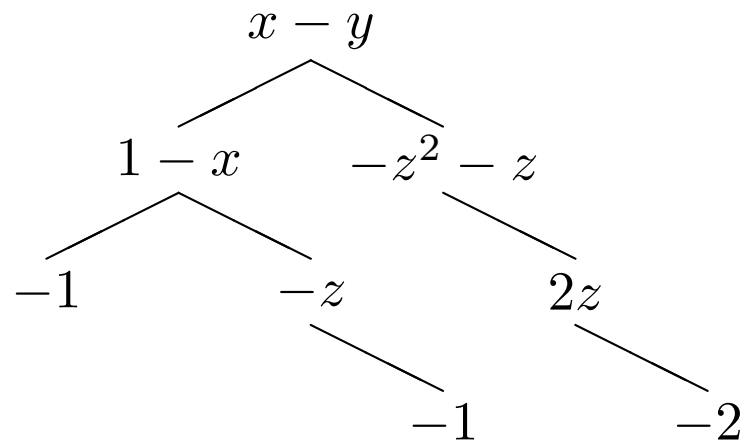
Remarks:

- Follows from earlier proposition.
- But also intuitive by itself.
- Simple: Form one FDT and examine.

Example

$$\tau_1 : \{x \geq y\} \rightarrow \{x' = x + 1, y' = y + x, z' = z\}$$

$$\tau_2 : \{x \geq y\} \rightarrow \{x' = x - z, y' = y + z^2, z' = z - 1\}$$



Check:

- Starting from the leaves, each node is found to be decreasing.
- Therefore, $x - y$ eventually only decreases.
- But $x \geq y$, so the loop terminates on all input.

Finite vs. Infinite FDT

- Finite FDT indicates qualitatively polynomial behavior: corresponds to finite number of nonzero derivatives.
- Infinite FDT indicates qualitatively exponential behavior: corresponds to infinite number of nonzero derivatives.
- But by the *standard condition*, if a node is proved to be at most some negative constant, then it is *decreasing*.

Idea: Use invariants to treat the infinite-FDT case.

Example

$$\theta : n, x, y, N \geq 0$$

$$\{x \leq N\} \rightarrow \{n' = n + 1, x' = nx + y, y' = y + 1, N' = N\}$$

Invariants: $n, x, y, N \geq 0$

$$\begin{array}{c} N - x \\ | \\ x - nx - y \\ | \\ -1 - x + nx - n^2x - ny \\ \vdots \end{array}$$

Remarks:

- $n, x, y \geq 0 \rightarrow -1 - x + nx - n^2x - ny \leq -1$
- Thus, the loop terminates on all input.

Experimental Results

Focus:

- Test scalability, applicability
- Code abstraction is currently naïve
- Suggest theoretical and practical refinements

Implementation:

- Written as a CIL feature.
- Abstracts C loops as sets of guarded commands.
- Applies **standard condition** to find *lexicographic* polyranking functions based on guards.

Experimental Results

Name	LOC	Loops	Abstract	Proved	P/A	P/L	Time (s)
small1	310	8	6	4	66	50	2
vector	361	13	13	12	92	92	2
serv	457	9	6	5	83	55	1
dcg	1K	55	53	53	100	96	3
bcc	4K	70	18	18	100	25	5
sarg	7K	108	25	25	100	23	104
spin	19K	652	132	121	91	18	30
meschach	28K	911	803	770	95	84	60
f2c	30K	437	113	96	84	21	52
libavformat	33K	452	268	216	80	47	55
gnuplot	50K	829	328	298	90	35	127
gaim	57K	594	60	52	86	8	106
libavcodec	75K	2227	1939	1869	96	83	183

Future Work

- Handle inequalities and more complex transition relations:
 - Can bound node expressions based on the **standard condition**.
- Rigorous code abstraction, *e.g.*,
 - aliasing,
 - interprocedural, possibly context-sensitive,
 - loop and function summaries as inequalities.
- Apply in complete verification frameworks (*e.g.*, *verification diagrams*).