# AN $O(N \cdot \log N)$ ALGORITHM FOR A CLASS OF MATCHING PROBLEMS* 

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#### Abstract

The following class of matching problems is considered. The vertices of a complete undirected graph are indexed $1, \cdots, n$, where $n=2 m$. Every vertex $i$ is assigned two numbers $a_{i}, b_{i}$. The length of every edge ( $i, j$ ), where $i<j$, is $d(i, j)=a_{i}+b_{j}$. This class of weighted graphs is applicable to scheduling and optimal assignment problems. A maximum weighted (perfect) matching is found in $O(n \cdot \log n)$ operations.


Key words. matching, assignment, scheduling, polynomial-time algorithm, 2-3 trees

1. Introduction. The maximum matching problem has many applications in operations research. The first polynomial-time bounded algorithm for the maximum weighted matching problem is Edmonds' [2]. The most efficient algorithm for the maximum (cardinality) matching, known to the authors, is Even and Kariv's [3]. Gabow [4] has the most efficient algorithm for the weighted matching. In this paper we focus on a subclass of maximum weighted matching problems (see $\S 2$ for a precise definition). Our study is motivated by the following two problems which are easily shown to belong to our class.

In the first problem, a group of individuals, ordered by seniority, is to be partitioned into teams, having the same mission. Each team consists of two posi-tions-a senior position and a junior one. The senior position must be manned by the more senior individual between the members of the teant. Assuming that we know the effectiveness of each individual in both the senior and the junior positions, we wish to maximize the total effectiveness of the teams.

The second problem is to schedule $2 m$ jobs to $m$ identical processors, two jobs to each processor, preserving the arrival ordering. The objective is to minimize the total flow time, or equivalently, the average waiting time of a job.

Using a dynamic programming approach, these two models can be solved in $O\left(m^{2}\right)$ time. In this paper we present an algorithm which solves the above problems in $O(m \cdot \log m)$ operations.
2. Preliminaries. Our goal is to develop an efficient algorithm for the following problem.

Problem 1. Given numbers $a_{i}, b_{i}, i=1, \cdots, n(n=2 m)$, find a perfect matching $\left(i_{1}, j_{1}\right), \cdots,\left(i_{m}, j_{m}\right)$, where $i_{k}<j_{k}, k=1, \cdots, m$, which maximizes $\sum_{k=1}^{m}\left(a_{i_{k}}+b_{i_{k}}\right)$.

We may assume without loss of generality that a maximum matching $\left(i_{1}, j_{1}\right), \cdots,\left(i_{m}, j_{m}\right)$ satisfies $i_{k}<i_{k+1}, j_{k}<j_{k+1}, k=1, \cdots, m-1$. In view of this we shall restrict our attention to matchings $\left(i_{1}, j_{1}\right), \cdots,\left(i_{m}, j_{m}\right)$ which satisfy $i_{k}<j_{k}, k=$ $1, \cdots, m$, and $i_{k}<i_{k+1}, j_{k}<j_{k+1}, k=1, \cdots, m-1$. These can be handled by introducing the following notation.

Let $x=\left(x_{1}, \cdots, x_{n}\right)$ be a vector whose components are either 1 or -1 . Denote $H_{i}(x)=\sum_{k=1}^{i} x_{k}, i=1, \cdots, n$. Let $X$ be the set of all vectors $x\left(x=\left(x_{1}, \cdots, x_{n}\right)\right.$, $\left.x_{i} \in\{1,-1\}\right)$ such that $H_{i}(x) \geqq 0, i=1, \cdots, n-1$ and $H_{n}(x)=0$. Consider the following problem.

[^0]Problem 2. Maximize $c(x) \equiv \sum_{i=1}^{n}\left(a_{i}-b_{i}\right) \cdot x_{i}$ over $X$.
We claim that Problems 1 and 2 are equivalent. Specifically, if $\left(i_{1}, j_{1}\right), \cdots,\left(i_{m}, j_{m}\right)$ solves Problem 1 then the vector $x$, where $x_{k}=1$ if $k=i_{q}$ and $x_{k}=-1$ if $k=j_{q}$, solves Problem 2. Conversely, if $x$ solves Problem 2 then a solution to Problem 1 is defined recursively as follows. Let $i_{1}=1$. Suppose that $i_{1}, \cdots, i_{q}$ and $j_{1}, \cdots, j_{r}(0 \leqq r \leqq q)$ have been defined, and $\left\{i_{1}, \cdots, i_{q}, j_{1}, \cdots, j_{r}\right\}=\{1, \cdots, q+r\}$. Then, if $x_{q+r+1}=1$ let $i_{q+1}=$ $q+r+1$ and if $x_{q+r+1}=-1$ let $j_{r+1}=q+r+1$. Thus, we shall henceforth be dealing with Problem 2. We note that Problem 2 can be transformed to a linear program with a cotally unimodular matrix whose basic solutions yield solutions to our problem. Thus, the theory of linear programming suffices for solving Problem 2. However, we shall present an algorithm which is more suitable. Our algorithm is based on the following theorem.

Theorem. A vector x solves Problem 2 if and only if the following condition holds. For every pair $i, j, 1 \leqq i<j \leqq n$, (i) if $x_{i}=-1, x_{j}=1$ then $a_{i}-b_{i} \leqq a_{j}-b_{j}$ and (ii) if $x_{i}=1$, $x_{j}=-1$ and $H_{k}(x) \geqq 2$, for $i \leqq k<j$, then $a_{i}-b_{i} \geqq a_{i}-b_{j}$.

Necessity is obvious, since if the condition does not hold, then by defining $y_{i}=-x_{i}, y_{j}=-x_{j}$, and $y_{k}=x_{k}$ for $k \neq i, j$ we have $y \in X$ and $c(y)>c(x)$. We shall now prove the sufficiency of the condition. For $x, y \in X$ define a metric $D(x, y)=$ $\#\left\{i: x_{i} \neq y_{i}\right\}$. Suppose that $x \in X$ does not solve Problem 2 and let $y \in X$ be a solution to Problem 2, which is nearest (with respect to (w.r.t.) $D$ ) to $x$. Let $i$ be the smallest index such that $x_{i}=1$ and $y_{i}=-1$. Let $j$ be the smallest index such that $x_{i}=-1$ and $y_{j}=1$. If $i>j$ then for every $k, j \leqq k<i, H_{k}(y) \geqq 2$. It follows that $a_{i}-b_{j}>a_{i}-b_{i}$ (equality cannot occur since it implies $D(x, z)<D(x, y), c(z)=c(y), z \in X$, where $z_{i}=1, z_{j}=-1, z_{k}=y_{k}$ for $k \neq i, j$ ). Thus, part (i) of the condition does not hold. If $i<j$ then for every $k, i \leqq k<j, H_{k}(x) \geqq 2$. Similar arguments imply $a_{i}-b_{i}>a_{i}-b_{i}$ and in this case part (ii) does not hold.
3. The algorithm. We shall first describe our algorithm in general terms and then elaborate on its details. In this section we concentrate on the validity of the algorithm; an estimate of the number of operations is given in $\S 4$.

Let $M_{1}=\{1, \cdots, m\}, M_{2}=\{m+1, \cdots, n\}$. For every $x \in X$ let

$$
\begin{aligned}
& I(x)=\min \left\{i \in M_{1}: H_{k}(x) \geqq 2 \text { for all } k, i \leqq k \leqq m\right\}, \\
& J(x)=\max \left\{j \in M_{2}: H_{k}(x) \geqq 2 \text { for all } k, m+1 \leqq k \leqq j-1\right\} .
\end{aligned}
$$

Our algorithm generates a sequence $x^{0}, \cdots, x^{r}$ of vectors in $X$ such that $D\left(x^{k-1}, x^{k}\right)=2$. This sequence develops according to the following scheme.

## Scheme.

0 . Initiate with $x=(1, \cdots, 1,-1, \cdots,-1) \in X$.

1. Find an $i \in M_{1}$ such that $x_{i}=1, \quad i \geqq I(x)$ and $a_{i}-b_{i}=$ $\min \left\{a_{k}-b_{k}: I(x) \leqq k \leqq m, x_{k}=1\right\}$; find a $j \in M_{2}$ such that $x_{i}=-1, j \leqq J(x)$ and $a_{i}-b_{j}=\max \left\{a_{k}-b_{k}: m+1 \leqq k \leqq J(x), x_{k}=-1\right\}$.
2: If $a_{i}-b_{i} \geqq a_{j}-b_{i}$ then terminate; otherwise, set $x_{i}=-1, x_{j}=1$ and go to 1 .
Let $x^{i}(i=0,1, \cdots)$ denote the vector $x$ stored after $i$ executions of step 2 , and suppose that the scheme terminates after $r$ iterations. It can be easily verified that $c\left(x^{k-1}\right)<c\left(x^{k}\right), k=1, \cdots, r$. Moreover, since $H_{m}\left(x^{k}\right)=m-2 k$ and $H_{m}\left(x^{k}\right) \geqq 0$ for $k=0,1, \cdots, r$, it follows that $r \leqq m / 2$.

We shall now prove that upon termination the vector $x=x^{\prime}$ is a solution to Problem 2. This is done by verifying that the condition stated in the theorem is satisfied. Let $i<j$ be any pair ( $1 \leqq i, j \leqq n$ ). Distinguish cases: (i) $x_{i}=-1, x_{j}=1$. If $i, j \in M_{1}$ then there is $q<r$ such that $x_{i}^{q}=1, i \geqq I\left(x^{q}\right)$ and $a_{i}-b_{i}=$
$\min \left\{a_{k}-b_{k}: I\left(x^{q}\right) \leqq k \leqq m, \quad x_{k}^{q}=1\right\}$. This implies $a_{i}-b_{i} \leqq a_{j}-b_{j}$. Analogous arguments hold in case $i, j \in M_{2}$. The case $i \in M_{1}, j \in M_{2}$ can be handled by applying this type of arguments twice. (ii) $x_{i}=1, x_{j}=-1$, and $H_{k}(x) \geqq 2$ for $i \leqq k<j$. If $i, j \in M_{1}$ then there is $q<r$ such that $x_{j}^{q}=1, j \geqq I\left(x^{q}\right)$ and $a_{j}-b_{j}=\min \left\{a_{k}-b_{k}: I\left(x^{q}\right) \leqq k \leqq m\right.$. $\left.x_{k}^{q}=1\right\}$. However, since $H_{k}\left(x^{q}\right) \geqq H_{k}(x)(k=1, \cdots, m)$, it follows that $i \geqq I\left(x^{q}\right)$ and hence $a_{i}-b_{i} \geqq a_{j}-b_{j}$. A similar argument holds in case $i, j \in M_{2}$. If $i \in M_{1}$ and $j \in M_{2}$ then termination implies $a_{i}-b_{i} \geqq a_{i}-b_{j}$.

In fact, the sequence $x^{0}, \cdots, x^{\prime}$ can be generated without calculating the values $I(x), J(x), H_{k}(x)$ explicitly. This can be performed as follows. First, the elements $i$ of $M_{1}$ are sorted according to increasing magnitude of $a_{i}-b_{i}$ and the elements $j$ of $M_{2}$ are sorted according to decreasing magnitude of $a_{j}-b_{j}$. Let $x^{q}$ be a vector in the sequence generated by the scheme. Let $A_{1}$ denote the ordered (by the natural order on $M_{1}$ ) $q$-tuple of the indices $i \in M_{1}$ such that $x_{i}^{q}=-1$. An index $i \in A_{1}$ is called a right minimum if $H_{i}\left(x^{q}\right)<H_{k}\left(x^{q}\right)$ for every $k \in M_{1}$ such that $k>i$. Let $B_{1}$ denote the ordered set of right minima. Linearly ordered sets $A_{2}, B_{2}$ are defined in analogous manner with respect to the elements in $M_{2} ; A_{2}$ is the ordered tuple of the indices $j \in M_{2}$ such that $x_{i+1}^{q}=1$ and $B_{2}$ consists of those $j \in A_{2}$ such that $H_{j}\left(x^{q}\right)<H_{k}\left(x^{q}\right)$ for every $k<j\left(k \in M_{2}\right)$. Once the lists $A_{1}, B_{1}, A_{2}, B_{2}$ (w.r.t. a vector $x$ ) are known, it is easy to execute step 1 of the scheme. The following algorithm generates the same sequence as that generated by the scheme, and at the same time maintains the lists $A_{1}, B_{1}, A_{2}, B_{2}$. Our algorithm operates symmetrically on the sets $M_{1}, M_{2}$. Hence we shall describe in detail only the part concerning $M_{1}$.

## Algorithm.

Phase I: Sort the elements $i$ of $M_{1}$ to form a list $L_{1}$ arranged in order of increasing magnitude of $a_{i}-b_{i}$; sort $M_{2}$ to form a list $L_{2}$ arranged in decreasing order.

Phase II:
0 . Initiate with $x=(1, \cdots, 1,-1, \cdots,-1) \in X$ and $A_{1}=B_{1}=A_{2}=B_{2}=\varnothing$.

1. Let $i$ be the first element in $L_{1}$ and let $s=\#\left\{k: k \in A_{1}, k<i\right\}$.
2. If $i-2 s<2$ then delete $i$ from $L_{1}$ and go to 1 ; otherwise go to 3 .
3. If there is no $k \in B_{1}$ such that $k>i$ then set $i^{*}=\infty, s^{*}=0$ and go to 5 ; otherwise let $i^{*}$ be the smallest element of $B_{1}$ such that $i^{*}>i$ and let $s^{*}=\#\left\{k: k \in A_{1}, k<i^{*}\right\}$.
4. If $i^{*}-2\left(s^{*}+1\right)<2$ then delete $i$ from $L_{1}$ and go to 1 ; otherwise go to 5 .
5. Pick an element $j \in M_{2}$ in a manner similar to that by which $i$ is picked from $M_{1}$ (see steps $1-4 ; j$ is the first in $L_{2}$ such that $2 m-(j-1)-2 t \geqq 2$, where $t=\#\left\{k: k \in A_{2}, k \geqq j\right\}$, and either there is no $k \in B_{2}$ such that $k<j$, or $2 m-j^{*}-2 t^{*} \geqq 2$, where $j^{*}$ is the largest element of $B_{2}$ such that $j^{*}<j-1$ and $\left.t^{*}=\#\left\{k: k \in A_{2}, k \geqq j^{*}\right\}\right)$.
6. If $a_{i}-b_{i} \geqq a_{j}-b_{j}$ then terminate; otherwise, set $x_{i}=-1, x_{j}=1$ and go to 7 .
7. Delete $i$ from $L_{1}$ and insert $i$ into $A_{1}$.
8. If $i-2(s+1) \geqq i^{*}-2\left(s^{*}+2\right)$ then set $i=i^{*}, s=s^{*}+1$ and go to 9 ; otherwise insert $i$ into $B_{1}$.
9. If there is no $k \in B_{1}$ such that $k<i$ then go to 11 ; otherwise let $i^{\prime}$ be the largest element of $B_{1}$ such that $i^{\prime}<i$ and let $s^{\prime}=\#\left\{k: k \in A_{1}, k<i^{\prime}\right\}$.
10. If $i^{\prime}-2\left(s^{\prime}+1\right)<i-2(s+1)$ then go to 11 ; otherwise delete $i^{\prime}$ from $B_{1}$ and go to 9 .
11. Perform on $j, A_{2}, B_{2}$ operations similar to those performed on $i, A_{1}, B_{1}$ in steps 7-10 (delete $j$ from $L_{2}$; insert $j-1$ into $A_{2}$, if $j>m+1$; insert $j-1$ into $B_{2}$ if it has become a "left minimum" and delete from $B_{2}$ those elements that have ceased from being left minima).
12. Go to 1 .
13. The efficiency of the algorithm. We may employ the device of a $2-3$ tree (see [1, p.146] for a precise definition) for handling the linearly ordered sets $A_{1}, B_{1}, A_{2}, B_{2}$ in our algorithm. Again, the symmetry enables us to restrict our attention to $A_{1}$ and $B_{1}$. Let $T$ be a 2-3 tree which represents $A_{1}$. For every vertex $v$ of $T$ which is not a leaf, $L[v]$ is the largest element of $A_{1}$ assigned to the subtree whose root is the leftmost son of $v ; M[v]$ is the largest element of $A_{1}$, assigned to the subtree whose root is the second son of $v$. For every vertex $v$ of $T$ let $a(v)$ denote the number of leaves of the subtree rooted in $v$, and let $b(v)$ denote the number of leaves of this subtree storing an element of $\boldsymbol{B}_{1}$.

It can be easily verified (see [1]) that each one of the following operations can be executed in at most $O(\log n)$ steps: (a) Find the smallest element of $A_{1}$ which is greater than a given $i \in M_{1}$. (b) Find the smallest [largest] element of $B_{1}$ which is greater [smaller] than a given $i \in M_{1}$. (c) Insert an element into $A_{1}$. (d) Insert an element of $A_{1}$ into $B_{1}$. (e) Calculate $s, s^{*}, s^{\prime}$.

Since each one of the operations listed above can be executed no more than $O(n)$ times in Phase II of our algorithm, and since these are essentially all the operations executed during Phase II, it follows that Phase II requires no more than $O(n \cdot \log n)$ steps. It is well-known that Phase I can also be executed in $O(n \cdot \log n)$ steps (see [1]).

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