

Invariant Generation

CS156: Calculus of Computation

Zohar Manna

Aaron R. Bradley

Outline

- ⇒ 0. Static Analysis
 - 1. Interval Analysis
 - 2. Karr's Analysis

Transition System

$$T : \langle V, L, \ell_0, \theta, \mathcal{T} \rangle$$

- V : variables, with domain $\text{domain}(V)$
- L : locations
- ℓ_0 : initial location
- θ : initial condition — assertion $\theta(V)$
- \mathcal{T} : transitions

$$\langle \ell, m, \rho \rangle \in \mathcal{T}$$

- ℓ : pre-location
- m : post-location
- ρ : transition relation — assertion $\rho(V, V')$

Example: Transition System

```
@ i = 0;  
while (...) {  
    i := i + 1;  
}
```

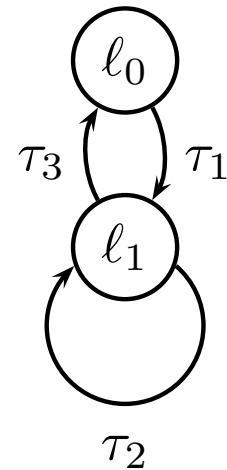
$$T_1 : \langle \underbrace{\{i : \mathbb{R}\}}_V, \underbrace{\{l_0\}}_L, l_0, \underbrace{i = 0}_\theta, \underbrace{\{\langle l_0, l_0, i' = i + 1 \rangle\}}_T \rangle$$

Example: Transition System

```

@ n ≥ 0;
for(i := 0; i < n; i := i + 1) {
  for(j := i - 1; j ≥ 0; j := j - 1) {
    ...
  }
}

```



$$T_2 : \langle \underbrace{\{i, j, n : \mathbb{R}\}}_V, \underbrace{\{l_0, l_1\}}_L, l_0, \underbrace{i = 0 \wedge n \geq 0}_\theta, \underbrace{\{\tau_1, \tau_2, \tau_3\}}_T \rangle$$

$$\tau_1 : \langle l_0, l_1, i < n \wedge i' = i \wedge j' = i - 1 \wedge n' = n \rangle$$

$$\tau_2 : \langle l_1, l_1, j \geq 0 \wedge i' = i \wedge j' = j - 1 \wedge n' = n \rangle$$

$$\tau_3 : \langle l_1, l_0, j < 0 \wedge i' = i + 1 \wedge j' = j \wedge n' = n \rangle$$

$$\text{domain}(V) = \mathbb{R} \times \mathbb{R} \times \mathbb{R}$$

Computation

$$\sigma = \langle \ell^1, \bar{x}_1 \rangle, \langle \ell^2, \bar{x}_2 \rangle, \langle \ell^3, \bar{x}_3 \rangle, \dots$$

- $\langle \ell^i, \bar{x}_i \rangle$
 - $\ell^i \in L$
 - $\bar{x}_i \in \text{domain}(V)$
- initially:
 - $\ell^1 = \ell_0$
 - $\theta(\bar{x}_1)$
- consecution:

$$(\forall i \geq 1)(\exists \langle \ell, m, \rho \rangle \in \mathcal{T})(\ell^i = \ell \wedge \ell^{i+1} = m \wedge \rho(\bar{x}_i, \bar{x}_{i+1}))$$

Example: $\langle \{i : \mathbb{R}\}, \{\ell_0\}, \ell_0, i = 0, \{\tau : \langle \ell_0, \ell_0, i' = i + 1 \rangle\} \rangle$

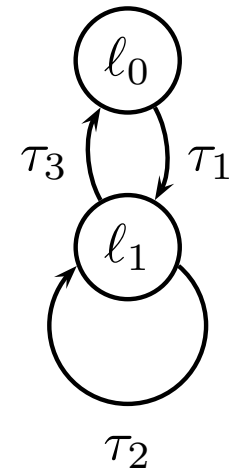
$$\langle \ell_0, \langle i : 0 \rangle \rangle, \langle \ell_0, \langle i : 1 \rangle \rangle, \langle \ell_0, \langle i : 2 \rangle \rangle, \dots$$

Example: Computation

```

@  $n \geq 0$ ;
for( $i := 0; i < n; i := i + 1$ ) {
  for( $j := i - 1; j \geq 0; j := j - 1$ ) {
    ...
  }
}

```



```

...    $\langle l_0, \langle i : 3, j : -1, n : 4 \rangle \rangle$ 
 $\xrightarrow{\tau_1}$   $\langle l_1, \langle i : 3, j : 2, n : 4 \rangle \rangle$ 
 $\xrightarrow{\tau_2}$   $\langle l_1, \langle i : 3, j : 1, n : 4 \rangle \rangle$ 
 $\xrightarrow{\tau_2}$   $\langle l_1, \langle i : 3, j : 0, n : 4 \rangle \rangle$ 
 $\xrightarrow{\tau_2}$   $\langle l_1, \langle i : 3, j : -1, n : 4 \rangle \rangle$ 
 $\xrightarrow{\tau_3}$   $\langle l_0, \langle i : 4, j : -1, n : 4 \rangle \rangle$ 

```

Collecting Semantics

$$\mathcal{C} : L \rightarrow 2^{\text{domain}(V)}$$

- map from locations to subsets of $\text{domain}(V)$
- $\mathcal{C}(\ell)$: the set of values (in $\text{domain}(V)$) that occur at ℓ during some computation:

$$\bar{x} \in \mathcal{C}(\ell)$$



$$(\exists \sigma = \langle \ell^1, \bar{x}_1 \rangle, \langle \ell^2, \bar{x}_2 \rangle, \langle \ell^3, \bar{x}_3 \rangle, \dots)(\exists i)(\ell_i = \ell \wedge \bar{x}_i = \bar{x})$$

Example: $\langle \{i : \mathbb{R}\}, \{\ell_0\}, \ell_0, i = 0, \{\tau : \langle \ell_0, \ell_0, i' = i + 1 \rangle\} \rangle$

$$\mathcal{C}(\ell_0) = \{ \langle i : n \rangle : n \in \mathbb{Z}^+ \}$$

Example: Collecting Semantics

$$T : \langle \{i, j, n : \mathbb{R}\}, \{\ell_0, \ell_1\}, \ell_0, i = 0 \wedge n \geq 0, \{\tau_1, \tau_2, \tau_3\} \rangle$$

$$\tau_1 : \langle \ell_0, \ell_1, i < n \wedge i' = i \wedge j' = i - 1 \wedge n' = n \rangle$$

$$\tau_2 : \langle \ell_1, \ell_1, j \geq 0 \wedge i' = i \wedge j' = j - 1 \wedge n' = n \rangle$$

$$\tau_3 : \langle \ell_1, \ell_0, j < 0 \wedge i' = i + 1 \wedge j' = j \wedge n' = n \rangle$$

$$\mathcal{C}(\ell_0) = \{ \langle i : I, j : J, n : N \rangle : 0 \leq I \leq N \wedge I \in \mathbb{Z} \}$$

$$\mathcal{C}(\ell_1) = \left\{ \langle i : I, j : J, n : N \rangle : \begin{array}{l} 0 \leq I \leq N \wedge -1 \leq J < I \\ \wedge I, J \in \mathbb{Z} \end{array} \right\}$$

Assertion Map

$$\mu : L \rightarrow \mathcal{A}(V)$$

- map from locations to assertions over V

$$\mathcal{S} : \mathcal{A}(V) \rightarrow 2^{\text{domain}(V)}$$

- map from assertions to subsets of $\text{domain}(V)$
- $\mathcal{S}(\varphi) = \{\bar{x} \in \text{domain}(V) : \varphi(\bar{x})\}$

Example: $\langle \{i : \mathbb{R}\}, \{\ell_0\}, \ell_0, i = 0, \{\tau : \langle \ell_0, \ell_0, i' = i + 1 \rangle\} \rangle$

- $\mu(\ell_0) : i \geq 0$
- $\mathcal{S}(i \geq 0) = \{\langle i : n \rangle : n \in \mathbb{R}^+\}$

Invariant Assertion Map

Assertion map

$$\mu : L \rightarrow \mathcal{A}(V)$$

such that

$$(\forall \ell \in L)(\mathcal{C}(\ell) \subseteq \mathcal{S}(\mu(\ell)))$$

i.e., $\mu(\ell)$ is an **over approximation** to $\mathcal{C}(\ell)$.

Alternately,

$$(\forall \ell \in L)(\forall \bar{x} \in \text{domain}(V))(\bar{x} \in \mathcal{C}(\ell) \rightarrow \mu(\ell)(\bar{x}))$$

Example: $\langle \{i : \mathbb{R}\}, \{\ell_0\}, \ell_0, i = 0, \{\tau : \langle \ell_0, \ell_0, i' = i + 1 \rangle\} \rangle$

- $\mathcal{C}(\ell_0) = \{\langle i : n \rangle : n \in \mathbb{Z}^+\} \subseteq \{\langle i : n \rangle : n \in \mathbb{R}^+\} = \mathcal{S}(\mu(\ell_0))$
- so $\mu(\ell_0) : i \geq 0$ is an invariant map

Example: Invariant Assertion Map

$$\mu(\ell_0) : 0 \leq i$$

$$\mu(\ell_1) : 0 \leq i \wedge -1 \leq j$$

So

$$\mathcal{S}(\mu(\ell_0)) = \{\langle i : I, j : J, n : N \rangle : 0 \leq I\}$$

$$\supseteq \{\langle i : I, j : J, n : N \rangle : 0 \leq I \leq N \wedge I \in \mathbb{Z}\}$$

$$\mathcal{S}(\mu(\ell_1)) = \{\langle i : I, j : J, n : N \rangle : 0 \leq I \wedge -1 \leq J\}$$

$$\supseteq \left\{ \langle i : I, j : J, n : N \rangle : \begin{array}{l} 0 \leq I \leq N \wedge -1 \leq J < I \\ \wedge I, J \in \mathbb{Z} \end{array} \right\}$$

μ is an **invariant map**:

$$\mathcal{C}(\ell_0) \subseteq \mathcal{S}(\mu(\ell_0)) \quad \text{and} \quad \mathcal{C}(\ell_1) \subseteq \mathcal{S}(\mu(\ell_1))$$

Inductive Assertion Map

Assertion map

$$\mu : L \rightarrow \mathcal{A}(V)$$

such that

Initiation

$$\theta \models \mu(\ell_0)$$

$$i.e., (\forall \bar{x} \in \text{domain}(V))(\theta(\bar{x}) \rightarrow \mu(\ell_0)(\bar{x}))$$

Consecution for all $\langle \ell, m, \rho \rangle \in \mathcal{T}$

$$\mu(\ell) \wedge \rho \models \mu(m)'$$

$$i.e., (\forall \bar{x}, \bar{x}' \in \text{domain}(V))(\mu(\ell)(\bar{x}) \wedge \rho(\bar{x}, \bar{x}') \rightarrow \mu(m)(\bar{x}'))$$

Example: Inductive Assertion Map

$$\langle \{i : \mathbb{R}\}, \{\ell_0\}, \ell_0, i = 0, \{\tau : \langle \ell_0, \ell_0, i' = i + 1 \rangle\} \rangle$$

$\mu(\ell_0) : i \geq 0$ is an inductive map:

Initiation $\theta \models \mu(\ell_0)$

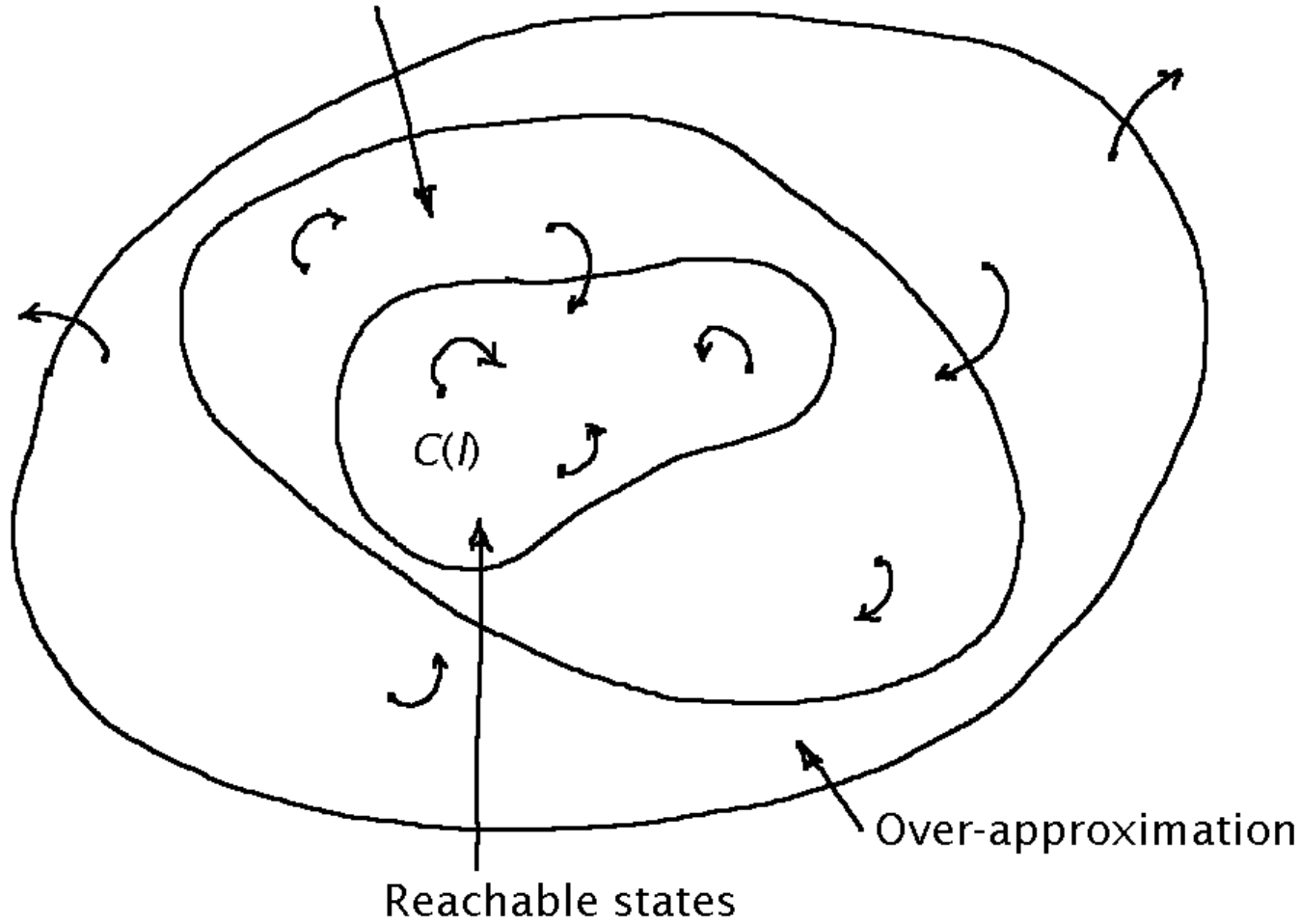
$$(\forall i)(i = 0 \rightarrow i \geq 0)$$

Consecution $\mu(\ell_0) \wedge i' = i + 1 \models \mu(\ell_0)'$

$$(\forall i, i')(i \geq 0 \wedge i' = i + 1 \rightarrow i' \geq 0)$$

Invariants: In Pictures

Inductive over-approximation



Example: Invariant vs. Inductive Invariant

$$T_3 : \langle \{n : \mathbb{R}\}, \{\ell_0\}, \ell_0, n = 1, \{\langle \ell_0, \ell_0, n' = -n \rangle\} \rangle$$

- Collecting semantics: $\mathcal{C}(\ell_0) = \{\langle n : -1 \rangle, \langle n : 1 \rangle\}$
- Invariant map: $\mu_1(\ell_0) : n \leq 1$
 - $\mathcal{C}(\ell_0) \subseteq \mathcal{S}(\mu_1(\ell_0))$
 - But not **inductive**:

$$(\forall n, n')(n \leq 1 \wedge n' = -n \rightarrow n' \leq 1)$$

is invalid — consider $n = -3, n' = 3$.

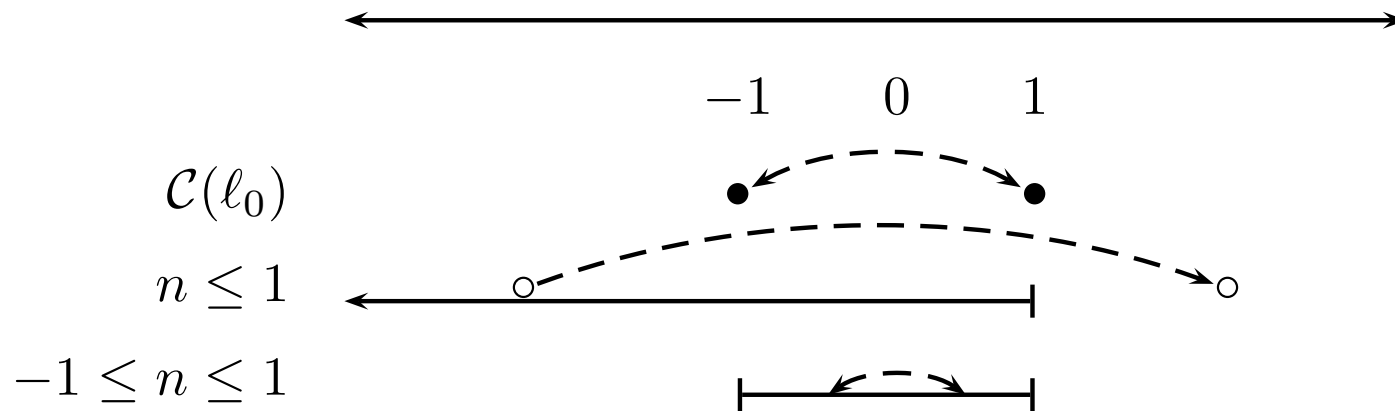
- Inductive map: $\mu_2(\ell_0) : -1 \leq n \leq 1$
 - $\mathcal{C}(\ell_0) \subseteq \mathcal{S}(\mu_2(\ell_0))$
 - Initiation: $(\forall n)(n = 1 \rightarrow -1 \leq n \leq 1)$
 - Consecution:

$$(\forall n, n')(-1 \leq n \leq 1 \wedge n' = -n \rightarrow -1 \leq n' \leq 1)$$

Example: Invariant *vs.* Inductive Invariant

$$\langle \{n : \mathbb{R}\}, \{\ell_0\}, \ell_0, n = 1, \{\langle \ell_0, \ell_0, n' = -n \rangle\} \rangle$$

In pictures:



All are invariants, but only $\mathcal{C}(\ell_0)$ and $-1 \leq n \leq 1$ are inductive.

Post

$$\text{post} : \mathcal{A}(V) \times \mathcal{T} \rightarrow \mathcal{A}(V)$$

- map from assertions and transitions to assertions
- general definition:

$$\text{post}(\varphi, \langle \ell, m, \rho \rangle) = (\exists \bar{x}^0)(\varphi(\bar{x}^0) \wedge \rho(\bar{x}^0, \bar{x}))$$

- $\text{post}(\varphi, \tau)$ holds on the τ -successors of φ -states

Example: $\langle \{i : \mathbb{R}\}, \{\ell_0\}, \ell_0, i = 0, \{\tau : \langle \ell_0, \ell_0, i' = i + 1 \rangle\} \rangle$

$$\begin{aligned} \text{post}(\mu(\ell_0), \tau) &= \text{post}(i \geq 0, \tau) \\ &= (\exists i_0)(i_0 \geq 0 \wedge i = i_0 + 1) \\ &\Leftrightarrow i \geq 1 \end{aligned}$$

Inductive Map Using Post

Initiation

$$\theta \models \mu(\ell_0)$$

Consecution for all $\langle \ell, m, \rho \rangle \in \mathcal{T}$

$$\text{post}(\mu(\ell), \langle \ell, m, \rho \rangle) \models \mu(m)$$

Example: $\langle \{i : \mathbb{R}\}, \{\ell_0\}, \ell_0, i = 0, \{\tau : \langle \ell_0, \ell_0, i' = i + 1 \rangle\} \rangle$

Initiation $\theta \models \mu(\ell_0)$

$$(\forall i)(i = 0 \rightarrow i \geq 0)$$

Consecution $\text{post}(\mu(\ell_0), \tau) \models \mu(\ell_0)$

$$(\forall i)((\exists i_0)(i_0 \geq 0 \wedge i = i_0 + 1) \rightarrow i \geq 0)$$



$$(\forall i)(i \geq 1 \rightarrow i \geq 0)$$

Example: Inductive Map Using Post

$$\text{post}(\mu(\ell_0), \tau_1)$$

$$= \text{post}(0 \leq i, \langle \ell_0, \ell_1, i \leq n \wedge i' = i \wedge j' = i - 1 \wedge n' = n \rangle)$$

$$= (\exists i_0, n_0)(0 \leq i_0 \wedge i_0 \leq n_0 \wedge i = i_0 \wedge j = i_0 - 1 \wedge n = n_0)$$

$$= 0 \leq i \wedge i \leq n \wedge j = i - 1$$

$$\models \mu(\ell_1) : 0 \leq i \wedge -1 \leq j$$

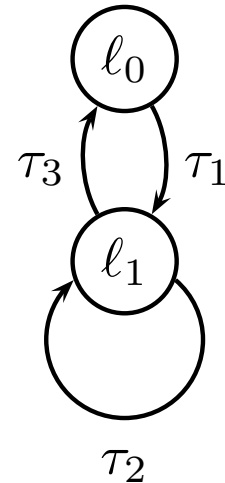
$$\text{post}(\mu(\ell_1), \tau_2) = 0 \leq i \wedge -1 \leq j$$

$$\models \mu(\ell_1) : 0 \leq i \wedge -1 \leq j$$

$$\text{post}(\mu(\ell_1), \tau_3) = 1 \leq i \wedge -1 \leq j$$

$$\models \mu(\ell_0) : 0 \leq i$$

$\Rightarrow \mu$ is an **inductive map**.



Forward Propagation (FP)

$FP(T : \langle V, L, \ell_0, \theta, \mathcal{T} \rangle)$

$\mu(\ell_0) := \theta$

$\mu(\ell) := \text{false}$ for $\ell \in L \setminus \{\ell_0\}$

$Q := \{\ell_0\}$

while ($|Q| > 0$) do

$\underline{\ell} := \text{choose}(Q)$

 for each $\tau := \langle \underline{\ell}, m, \rho \rangle \in \mathcal{T}$ do

 if $\text{post}(\mu(\underline{\ell}), \tau) \neq \mu(m)$

 then $\mu(m) := \mu(m) \vee \text{post}(\mu(\underline{\ell}), \tau)$

$Q := Q \cup \{m\}$

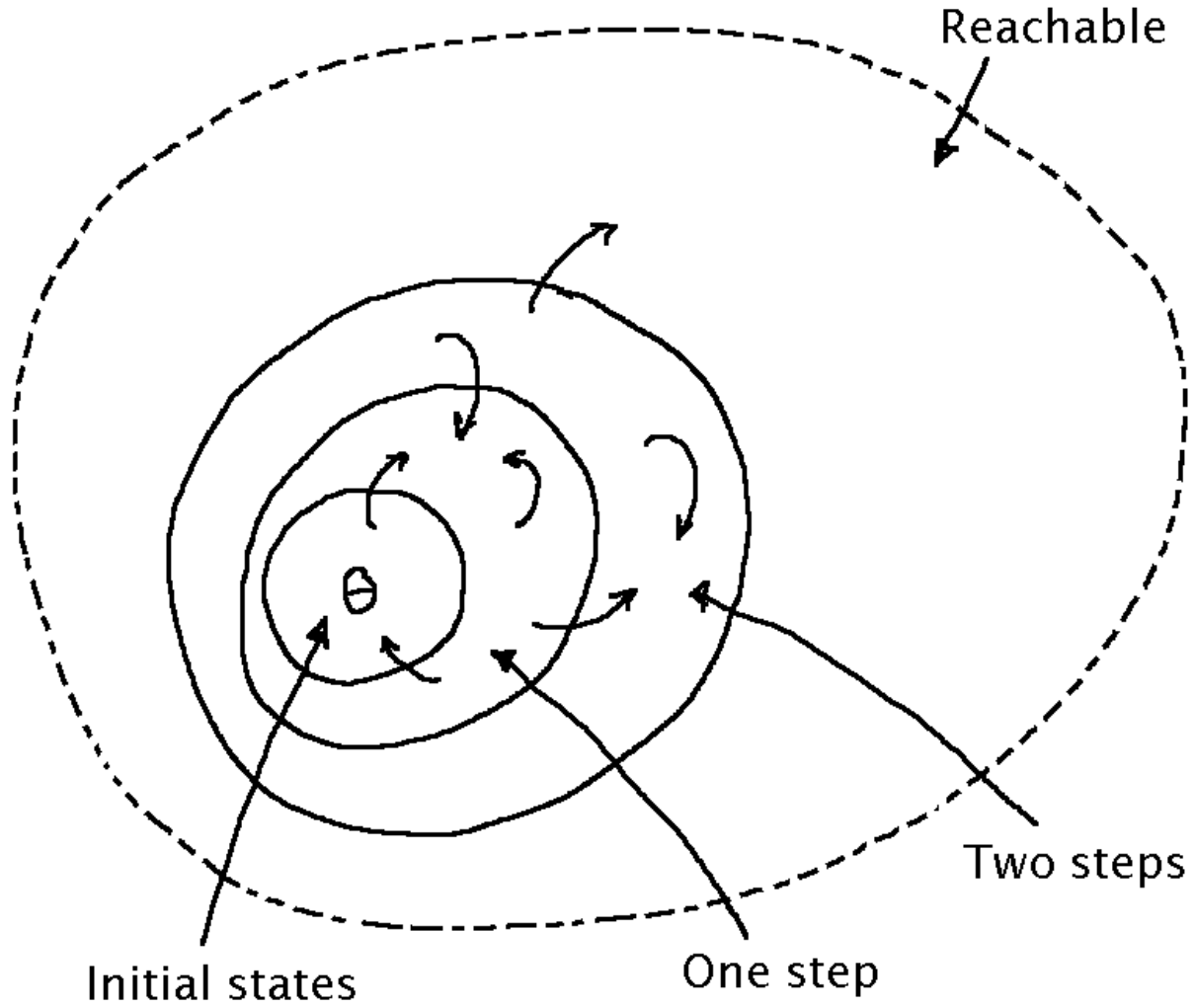
 done

done

If FP terminates, then the computed μ is an inductive map.

In fact, $\mathcal{S}(\mu(\ell)) = \mathcal{C}(\ell)$.

FP: In Pictures



FP: Remarks

- Computing

$$\text{post}(\mu(\ell), \tau) \models \mu(m)$$

requires checking FOL validity in general — undecidable!

- No guarantee of convergence.

Example: $\langle \{i : \mathbb{R}\}, \{\ell_0\}, \ell_0, i = 0, \{\tau : \langle \ell_0, \ell_0, i' = i + 1 \rangle\} \rangle$

– Initially: $\mu(\ell_0) := \theta \Rightarrow \mu(\ell_0) := i = 0$

– After N iterations:

$$\underbrace{\text{post} \left(\bigvee_{n=0}^N i = n, \tau \right)}_{\bigvee_{n=1}^{N+1} i = n} \not\models \bigvee_{n=0}^N i = n$$

$$\Rightarrow \mu(\ell_0) := \bigvee_{n=0}^{N+1} i = n$$

FP: Finite State Systems

Claim:

FP is an algorithm for computing the collecting semantics of Boolean circuits.

1. $\text{post}(\mu(\ell), \tau) \models \mu(m)$ is decidable (PL validity).
2. $\mu(\ell)$ can change only a finite number of times:
 - If $\text{post}(\mu(\ell), \tau) \not\models \mu(m)$, then $\mathcal{S}(\mu(m))$ becomes larger ($\mu(m) := \mu(m) \vee \text{post}(\mu(\ell), \tau)$).
 - $|2^{\text{domain}(V)}| = 2^{2^{|V|}}$ is finite.
 - $\mathcal{S}(\mu(\ell))$ can only increase a finite number of times.

Applications:

- Explicit-state model checking: compute sets of bit-vectors.
- Symbolic model checking: represent sets with Boolean formulae (BDD representation).

FP: Infinite State Systems (General Programs)

1. Computing

$$\text{post}(\mu(\ell), \tau) \models \mu(m)$$

is undecidable in general.

\Rightarrow Choose decidable assertion domain (*e.g.*, $T_{\mathbb{R}}$, $T_{\mathbb{Z}}$, *etc.*).

2. FP does not converge in general.

\Rightarrow Guess approximating assertion (**widen**).

Assertion Domains

Goal: Make $\text{post}(\mu(\ell), \tau) \models \mu(m)$ decidable.

Domains:

- Intervals: conjunctions of simple inequalities

$$\bigwedge_i l_i \leq x_i \leq u_i \quad \text{for } l_i, u_i \in \mathbb{R} \cup \{-\infty, \infty\}$$

- $T_{\mathbb{R}}^=$: conjunctions of affine equations (Karr's analysis)

$$\sum_j a_j x_j = b$$

- $T_{\mathbb{R}}$: conjunctions of affine inequalities (polyhedra)

$$\sum_j a_j x_j \geq b$$

Assertion Domains

- $T_{\mathbb{Z}}$: conjunctions of affine inequalities

$$\sum_j a_j x_j \geq b$$

- Boolean combinations of fixed set of predicates
(predicate abstraction)

$$\{x > 0, x < -3, \text{null}(a), \dots\} \quad \text{null}(a) \vee x > 0$$

- ...

Outline

- 0. Static Analysis
- ⇒ 1. Interval Analysis
- 2. Karr's Analysis

Interval Domain

$$T : \langle V = \bar{x} = \{x_1, \dots, x_n\}, L, \ell_0, \theta, \mathcal{T} \rangle$$

Representation:

- $\widehat{\mathbb{R}} = \mathbb{R} \cup \{-\infty, \infty\}$
- $[\mathbf{l}, \mathbf{u}] = [\ell_1, u_1] \times \dots \times [\ell_n, u_n]$
where $[\mathbf{l}, \mathbf{u}]$ for $\mathbf{l}, \mathbf{u} \in \widehat{\mathbb{R}}^n$
- $[\infty, -\infty]$ is the canonical representation of the empty interval
 - $[\ell, u]$ where $\ell > u \Rightarrow [\infty, -\infty]$
 - convention: $[\infty, -\infty] + [-\infty, \infty] = [\infty, -\infty]$

Domain element: $[\mathbf{l}, \mathbf{u}]$

$$\bar{x} \in [\mathbf{l}, \mathbf{u}] \Leftrightarrow \bigwedge_i x_i \in [\ell_i, u_i] \Leftrightarrow \bigwedge_i \ell_i \leq x_i \leq u_i$$

Interval Arithmetic

Standard manipulations, *e.g.*:

- $\min[\ell, u] = \ell$
- $\max[\ell, u] = u$
- $[\ell_1, u_1] + [\ell_2, u_2] = [\ell_1 + \ell_2, u_1 + u_2]$
- for a constant c ,

$$c[\ell_1, u_1] = \begin{cases} [c\ell_1, cu_1] & c \geq 0 \\ [cu_1, c\ell_1] & c < 0 \end{cases}$$

Interval Logic

- Disjunction:

$$\begin{aligned}x \in [\ell_1, u_1] \vee x \in [\ell_2, u_2] &\Leftrightarrow x \in [\ell_1, u_1] \cup [\ell_2, u_2] \\ &\Rightarrow x \in [\min(\ell_1, \ell_2), \max(u_1, u_2)]\end{aligned}$$

Called the **interval hull**. Over approximation!

Ex: $[1, 3] \cup [5, \infty] = [1, \infty]$

- Conjunction:

$$\begin{aligned}x \in [\ell_1, u_1] \wedge x \in [\ell_2, u_2] &\Leftrightarrow x \in [\ell_1, u_1] \cap [\ell_2, u_2] \\ &\Leftrightarrow x \in \underbrace{[\max(\ell_1, \ell_2), \min(u_1, u_2)]}_{[\infty, -\infty] \text{ if necessary}}\end{aligned}$$

Ex: $[1, 3] \cap [2, \infty] = [2, 3]$

Post: Assignment

Use basic operations to define post efficiently:

$$\begin{aligned} \text{post}([\mathbf{l}, \mathbf{u}], x'_k = \sum_j a_j x_j \wedge \bigwedge_{i \neq k} x'_i = x_i) \\ &= (\exists \bar{x}^0) \left(\bar{x}^0 \in [\mathbf{l}, \mathbf{u}] \wedge x_k = \sum_j a_j x_j^0 \wedge \bigwedge_{i \neq k} x_i = x_i^0 \right) \\ &= x_k \in \sum_j a_j [\ell_j, u_j] \wedge \bigwedge_{i \neq k} x_i \in [\ell_i, u_i] \\ &= [\ell_1, u_1] \times \cdots \times \underbrace{\left[\min \sum_j a_j [\ell_j, u_j], \max \sum_j a_j [\ell_j, u_j] \right]}_{x_k} \cdots \times [\ell_n, u_n] \end{aligned}$$

Example:

$$\begin{aligned} \text{post}([-1, 3] \times [5, \infty], x'_1 = x_1 \wedge x'_2 = x_2 + 3x_1) \\ &= [-1, 3] \times ([5, \infty] + 3[-1, 3]) = [-1, 3] \times [2, \infty] \end{aligned}$$

Post: Assignment

If the assignment cannot be handled within interval domain:

$$\begin{aligned} \text{post}([\mathbf{l}, \mathbf{u}], x'_k = ? \wedge \bigwedge_{i \neq k} x'_i = x_i) \\ = [\ell_1, u_1] \times \cdots \underbrace{[-\infty, \infty]}_{x_k} \cdots \times [\ell_n, u_n] \end{aligned}$$

Example:

$$\begin{aligned} \text{post}([-1, 3] \times [5, \infty], x'_1 = x_1 \wedge x'_2 = x_2 + \mathbf{f}(3x_1)) \\ = [-1, 3] \times [-\infty, \infty] \end{aligned}$$

Post: Guard

$$\begin{aligned} \text{post}([\mathbf{l}, \mathbf{u}], ax_k \geq b \wedge \bar{x}' = \bar{x}) & \text{ for } a > 0 \\ & = (\exists \bar{x}^0) \left(\bar{x}^0 \in [\mathbf{l}, \mathbf{u}] \wedge x_k^0 \in \left[\frac{b}{a}, \infty \right] \wedge \bar{x} = \bar{x}^0 \right) \\ & = [\ell_1, u_1] \times \cdots \underbrace{\left[\max \left(\ell_k, \frac{b}{a} \right), \min(u_k, \infty) \right]}_{x_k} \cdots \times [\ell_n, u_n] \end{aligned}$$

Similar for $ax_k \leq b$ and $ax_k = b$, for $a > 0$.

$$\mathbf{Ex:} \text{ post}([1, 3] \times [-2, 9], x_2 \geq 0 \wedge \bar{x}' = \bar{x}) = [1, 3] \times [0, 9]$$

If the guard cannot be handled within interval domain:

$$\text{post}([\mathbf{l}, \mathbf{u}], ? \wedge \bar{x}' = \bar{x}) = [\mathbf{l}, \mathbf{u}]$$

$$\mathbf{Ex:} \text{ post}([1, 3] \times [-2, 9], x_2 \% 2 = 0 \wedge \bar{x}' = \bar{x}) = [1, 3] \times [-2, 9]$$

Post: Guard

General affine guard:

$$\begin{aligned} \text{post}([\mathbf{l}, \mathbf{u}], \sum_j a_j x_j \geq b \wedge \bar{x}' = \bar{x}) \\ &= (\exists \bar{x}^0) \left(\bar{x}^0 \in [\mathbf{l}, \mathbf{u}] \wedge \sum_j a_j x_j \geq b \wedge \bar{x} = \bar{x}^0 \right) \\ &= \max \sum_j a_j [\ell_j, u_j] \geq b \wedge \bar{x} \in [\mathbf{l}, \mathbf{u}] \\ &= \begin{cases} [\mathbf{l}, \mathbf{u}] & \text{if } \max \sum_j a_j [\ell_j, u_j] \geq b \\ [\infty, -\infty]^n & \text{otherwise} \end{cases} \end{aligned}$$

Example:

$$\text{post}([-\infty, 0] \times [1, \infty], x_1 \geq x_2 \wedge \bar{x}' = \bar{x}) = [\infty, -\infty] \times [\infty, -\infty]$$

$$\text{post}([-\infty, 100] \times [1, \infty], x_2 \geq x_1 \wedge \bar{x}' = \bar{x}) = [-\infty, 100] \times [1, \infty]$$

Post

In interval domain,

- post maps hypercubes to hypercubes
- post can be computed efficiently — no QE
- $\text{post}(\mu(\ell), \tau) \models \mu(m)$ can be checked efficiently:

$$(\forall \bar{x})(\bar{x} \in [\mathbf{l}^1, \mathbf{u}^1] \rightarrow \bar{x} \in [\mathbf{l}^2, \mathbf{u}^2])$$



$$\bigwedge_i (\ell_i^1 \geq \ell_i^2 \wedge u_i^1 \leq u_i^2)$$

i.e., check containment $[\mathbf{l}^1, \mathbf{u}^1] \subseteq [\mathbf{l}^2, \mathbf{u}^2]$

Example

$$T_3 : \langle \{n : \mathbb{R}\}, \{\ell_0\}, \ell_0, n = 1, \{\langle \ell_0, \ell_0, n' = -n \rangle\} \rangle$$

- $\mu(\ell_0) := [1, 1]$
- $\text{post}([1, 1], \langle \ell_0, \ell_0, n' = -n \rangle) = [-1, -1]$
 - $\text{post}(\mu(\ell), \tau) \models \mu(m)$?
No: $[-1, -1] \not\subseteq [1, 1]$
 - $\mu(\ell_0) := [1, 1] \cup [-1, -1] = [-1, 1]$
- $\text{post}([-1, 1], \langle \ell_0, \ell_0, n' = n \rangle) = [-1, 1]$
 - $\text{post}(\mu(\ell), \tau) \models \mu(m)$?
Yes: $[-1, 1] \subseteq [-1, 1]$

$\mu(\ell_0) = [-1, 1]$, *i.e.*, $\mu(\ell_0) : -1 \leq n \leq 1$ is an inductive map.

Convergence

$$\langle \{i : \mathbb{R}\}, \{\ell_0\}, \ell_0, i = 0, \{\tau : \langle \ell_0, \ell_0, i' = i + 1 \rangle\} \rangle$$

- $\mu(\ell_0) := [0, 0]$
- $\text{post}([0, 0], \langle \ell_0, \ell_0, i' = i + 1 \rangle) = [1, 1]$
 - $\text{post}(\mu(\ell), \tau) \models \mu(m)$?
No: $[1, 1] \not\subseteq [0, 0]$
 - $\mu(\ell_0) := [0, 0] \cup [1, 1] = [0, 1]$
- $\text{post}([0, 1], \langle \ell_0, \ell_0, i' = i + 1 \rangle) = [1, 2]$
 - $\text{post}(\mu(\ell), \tau) \models \mu(m)$?
No: $[1, 2] \not\subseteq [0, 1]$
 - $\mu(\ell_0) := [0, 1] \cup [1, 2] = [0, 2]$
- After n iterations: $\mu(\ell_0) := [0, n] \cup [1, n + 1] = [0, n + 1]$

FP does not converge on interval domain!

Widen

Goal: Guess over approximation to force convergence.

Interval widening:

- $[l_1, u_1] \nabla [l_2, u_2] = \underbrace{[l_2 < l_1 ? -\infty : l_1]}_{ite(l_2 < l_1, -\infty, l_1)}, \underbrace{[u_2 > u_1 ? \infty : u_1]}_{ite(u_2 > u_1, \infty, u_1)}$
- Special case: widening with empty interval:

$$[\infty, -\infty] \nabla [l, u] = [l, u] \nabla [\infty, -\infty] = [\infty, -\infty]$$

Extend component-wise to $[l^1, u^1] \nabla [l^2, u^2]$.

Examples:

- $[1, 4] \nabla [1, 5] = [1, \infty]$
- $[1, 4] \nabla [0, 5] = [-\infty, \infty]$
- $[\infty, -\infty] \nabla [0, 5] = [\infty, -\infty]$

Widen Step

Suppose

$$\text{post}(\mu(\ell), \tau) \not\sqsubseteq \mu(m)$$

after many (how many?) iterations of FP.

Instead of

$$\mu(m) := \mu(m) \vee \text{post}(\mu(\ell), \tau)$$

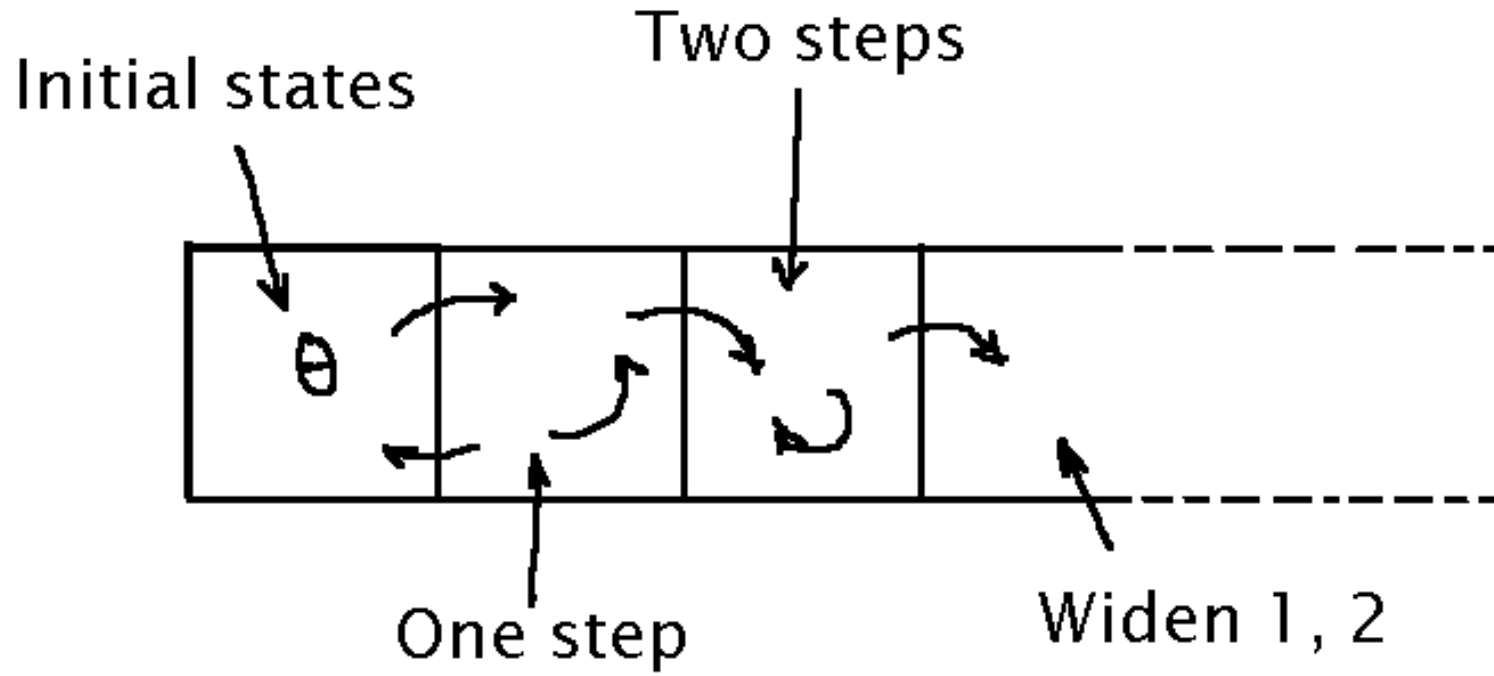
do

$$\mu(m) := \mu(m) \nabla (\mu(m) \vee \text{post}(\mu(\ell), \tau))$$

Remark:

μ is still an inductive map on termination of FP, but $\mathcal{C}(\ell) \subseteq \mathcal{S}(\mu(\ell))$ in general (instead of $\mathcal{C}(\ell) = \mathcal{S}(\mu(\ell))$).

Widen: In Pictures



Example: Widen

$$\langle \{i : \mathbb{R}\}, \{\ell_0\}, \ell_0, i = 0, \{\tau : \langle \ell_0, \ell_0, i' = i + 1 \rangle\} \rangle$$

- $\mu(\ell_0) := [0, 0]$
- $\text{post}([0, 0], \tau) = [1, 1]$
 - $\text{post}(\mu(\ell), \tau) \models \mu(m)$? No: $[1, 1] \not\subseteq [0, 0]$
 - $\mu(\ell_0) := [0, 0] \cup [1, 1] = [0, 1]$
- $\text{post}([0, 1], \tau) = [1, 2]$
 - $\text{post}(\mu(\ell), \tau) \models \mu(m)$? No: $[1, 2] \not\subseteq [0, 1]$
 - $\mu(\ell_0) := [0, 1] \nabla ([0, 1] \cup [1, 2]) = [0, \infty]$
- $\text{post}([0, \infty], \tau) = [1, \infty]$
 - $\text{post}(\mu(\ell), \tau) \models \mu(m)$? Yes: $[1, \infty] \subseteq [0, \infty]$

$\mu(\ell_0) = [0, \infty]$, *i.e.*, $\mu(\ell_0) : i \geq 0$ is an inductive map.

Standard Procedure

1. **(Domain)** Fix representation of class of assertions.
Ex: $[l, u]$
2. **(Post)** Define **post** efficiently with respect to domain.
Efficient definition must be over approximation of true **post**.
Ex: $\text{post}([l, u], \tau)$
3. **(Entailment)** Define efficient check of $\text{post}(\mu(l), \tau) \models \mu(m)$.
Ex: $[l^1, u^1] \subseteq [l^2, u^2]$
4. **(Disjunction)** Define over approximation of disjunction.
Used in step $\mu(m) := \mu(m) \vee \text{post}(\mu(l), \tau)$.
Ex: $[l^1, u^1] \cup [l^2, u^2]$ (interval hull)
5. **(Widen)** Define widen operation if FP does not converge.
Ex: $[l^1, u^1] \nabla [l^2, u^2]$

Outline

0. Static Analysis
1. Interval Analysis
- ⇒ 2. Karr's Analysis

Motivation

@ $i_1 = i_2 = k = 0$;

while (...) {

 if (...) {

$i_1 := i_1 + 1$;

$k := k + 1$;

 }

 else {

$i_2 := i_2 + 1$;

$k := k + 1$;

 }

}

$\langle \{i_1, i_2, k : \mathbb{R}\}, \{\ell_0\}, \ell_0, i_1 = i_2 = k = 0, \{\tau_1, \tau_2, \tau_3\} \rangle$

$\tau_1 : i'_1 = i_1 + 1 \wedge i'_2 = i_2 \wedge k' = k + 1$

$\tau_2 : i'_1 = i_1 \wedge i'_2 = i_2 + 1 \wedge k' = k + 1$

Goal: Deduce $i_1 + i_2 = k$.

1. Domain

$$T : \langle V = \{x_1, \dots, x_n\}, L, \ell_0, \theta, \mathcal{T} \rangle$$

Conjunctions of affine equations:

$$\bigwedge_{i=1}^m \left(\sum_j a_{i,j} x_j = b_i \right)$$

Dual representation:

1. (Constraint)

$$Ax = b$$

for $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^m$.

2. (Vertex) Basis X of $Ax = b$.

2. Post

- $\text{post}(S, x'_k = \sum_j a_j x_j + b \wedge \bigwedge_{i \neq k} x'_i = x_i)$
 - Application of affine transformation to affine space S .
 - Use vertex representation.
- $\text{post}(S, x'_k = ? \wedge \bigwedge_{i \neq k} x'_i = x_i)$
 - Non-affine assignment.
 - $\text{post}(S, x'_k = ? \dots) = \text{post}(S, x'_k = 0 \dots) \cup \text{post}(S, x'_k = 1 \dots)$
 - \cup defined below.
- $\text{post}(S, \sum_j a_j x_j = b \wedge \bar{x}' = \bar{x})$
 - Conjunction of two affine spaces (S and $\sum_j a_j x_j = b$).
 - Use constraint representation.
- $\text{post}(S, ? \wedge \bar{x}' = \bar{x}) = S$ (non-affine guard)

3, 4, 5

3. Entailment

$$\text{post}(\mu(\ell), \tau) \models \mu(m)$$

Check $S_1 \subseteq S_2$.

Use both representations.

4. Disjunction

Affine hull of the union of S_1 and S_2 .

Use vertex representation: $X_1 \cup X_2$

5. Widen

If $S_1 \subset S_2$, then $\dim(S_1) < \dim(S_2)$.

$$\dim(S) \leq n.$$

\Rightarrow FP converges on domain of affine equations.

\Rightarrow Widening is not needed.

Background: Linear Equation $Ax = 0$

$$Ax = 0$$

- A is an $m \times n$ matrix, *i.e.*, $A \in \mathbb{R}^{m \times n}$
- x is an n vector, *i.e.*, $x \in \mathbb{R}^n$
- 0 is an m vector, $[0 \ \dots \ 0]^T$

For us, $A \in \mathbb{Q}^{m \times n}$.

Example:

$$\underbrace{\begin{bmatrix} 3 & 0 & 2 \\ 1 & 1 & 0 \end{bmatrix}}_A \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}}_x = \underbrace{\begin{bmatrix} 0 \\ 0 \end{bmatrix}}_0$$

Background: Linear Space

Set of vectors:

Represent set of \mathbb{R}^n vectors

$$\{x^1, x^2, \dots, x^k\}$$

by $n \times k$ matrix

$$X = [x^1 \ x^2 \ \dots \ x^k] .$$

Notation: $|X| = k$

Linear space:

$$\text{lin}(X) = \left\{ \sum_{j=1}^m \lambda_j x_j \ : \ m \geq 0, \ x^j \in X, \ \lambda_j \in \mathbb{R} \right\}$$

X is a **basis** if for all $x \in X$, $x \notin \text{lin}(X - \{x\})$.

If X is a basis, then $|X| \leq n$.

Background: Affine Equation $Ax = b$

$$Ax = b$$

- A is an $m \times n$ matrix, *i.e.*, $A \in \mathbb{R}^{m \times n}$
- x is an n vector, *i.e.*, $x \in \mathbb{R}^n$
- b is an m vector, *i.e.*, $b \in \mathbb{R}^m$

For us, $A \in \mathbb{Q}^{m \times n}$, $b \in \mathbb{Q}^m$.

Example:

$$\underbrace{\begin{bmatrix} 3 & 0 & 2 \\ 1 & 1 & 0 \end{bmatrix}}_A \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}}_x = \underbrace{\begin{bmatrix} -1 \\ 0 \end{bmatrix}}_b$$

Background: Affine Space

Affine space:

$$\text{aff}(X) = \left\{ \sum_{j=1}^m \lambda_j x_j : m \geq 0, x^j \in X, \lambda_j \in \mathbb{R}, \sum_{j=1}^m \lambda_j = 1 \right\}$$

X is a **basis** if for all $x \in X$, $x \notin \text{aff}(X - \{x\})$.

If X is a basis, then $|X| \leq n + 1$.

What is the difference between linear and affine spaces?

All linear spaces contain the origin (0).

An affine space need not contain the origin.

Background: Elementary Operations

1. Interchange two rows.
2. Multiply row by nonzero scalar.
3. Add one row to another.

Applying elementary operations to A in

$$Ax = 0$$

does not change the set of solutions.

Applying elementary operations to $[A \ b]$ in

$$Ax = b$$

does not change the set of solutions.

Background: Row-Reduced Echelon Form (RREF)

- Each nonzero row has 1 as first nonzero entry.
- For column in which 1 is leading for a row, other entries are 0.
- Zero rows (if any) are at bottom of matrix.
- “Stairstep” pattern.

Example:

$$\begin{bmatrix} 1 & 0 & \frac{2}{3} & -\frac{1}{3} \\ 0 & 1 & -\frac{2}{3} & \frac{1}{3} \end{bmatrix}$$

Background: Solving $Ax = 0$

Solution to $Ax = 0$ is **null space** of A ,

$$y \in \text{lin}(\text{null}(A)) \Leftrightarrow Ay = 0$$

Computing $\text{null}(A)$:

- Put A in RREF.
- Free dimensions: $\{f_1, \dots, f_\ell\}$ s.t. no leading 1 in column f_i .
- Construct basis B :
 - $B_{f_i, i} = 1$
 - for $j = n$ to 1 do
 1. if row j is all zeros, $B_{j, i} = 0$ for $i \notin \{f_1, \dots, f_\ell\}$
 2. else some column i is leading 1: solve for $x_i = \sum a_k f_k$
 3. $B_{j, k} = a_k$
 4. substitute $\sum a_k f_k$ for x_i in rows 1 to $j - 1$

Example 1: $Ax = 0$

$$Ax = 0$$

$$\begin{bmatrix} 3 & 0 & 2 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$\text{null}(A)$:

- RREF:

$$\begin{bmatrix} 3 & 0 & 2 \\ 1 & 1 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & \frac{2}{3} \\ 1 & 1 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & \frac{2}{3} \\ 0 & 1 & -\frac{2}{3} \end{bmatrix}$$

- Free dimensions: $\{3\}$

Example 1: $Ax = 0$

$$\begin{bmatrix} 1 & 0 & \frac{2}{3} \\ 0 & 1 & -\frac{2}{3} \end{bmatrix}$$

- Construct basis B :

- $B_0 = [? ? 1]^\top$

- $j = 3$

- $B_1 = [? ? 1]^\top$

- $j = 2$

- $x_2 - \frac{2}{3}x_3 = 0 \Rightarrow x_2 = \frac{2}{3}x_3$

- $B_2 = [? \frac{2}{3} 1]^\top$

- substitute into row 1: no change

- $j = 1$

- $x_1 + \frac{2}{3}x_3 = 0 \Rightarrow x_1 = -\frac{2}{3}x_3$

- $B_3 = [-\frac{2}{3} \frac{2}{3} 1]^\top$

$$\Rightarrow \text{null}(A) = [-2 \ 2 \ 3]^\top$$

Example 2: $Ax = 0$

$$Ax = 0$$

$$\begin{bmatrix} 3 & 0 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$\text{null}(A)$:

- RREF:

$$\begin{bmatrix} 3 & 0 & 2 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & \frac{2}{3} \end{bmatrix}$$

- Free dimensions: $\{2, 3\}$

Example 2: $Ax = 0$

$$\begin{bmatrix} 1 & 0 & \frac{2}{3} \end{bmatrix}$$

- Construct basis B :

$$- B_0 = \begin{bmatrix} ? & ? \\ 1 & ? \\ ? & 1 \end{bmatrix}$$

$$- j = 3, 2$$

$$B_1 = \begin{bmatrix} ? & ? \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$j = 1$$

$$x_1 + \frac{2}{3}x_3 = 0 \Rightarrow x_1 = -\frac{2}{3}x_3$$

$$B_2 = \begin{bmatrix} 0 & -\frac{2}{3} \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\Rightarrow \text{null}(A) = \begin{bmatrix} 0 & -2 \\ 1 & 0 \\ 0 & 3 \end{bmatrix}$$

Background: Solving $Ax = b$

- Put $[A \ b]$ in RREF.
- Solve from RREF for one solution z .
- Compute $\text{null}(A)$ (extract from RREF).
- Construct basis B :

$$\{z\} \cup \{z + x : x \in \text{null}(A)\}$$

Call B the **solution basis**, $\text{soln}(A, b)$.

$$y \in \text{aff}(\text{soln}(A, b)) \Leftrightarrow Ay = b$$

Example 3: $Ax = b$

$$\begin{bmatrix} 3 & 0 & 2 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

- RREF:

$$\left[\begin{array}{ccc|c} 3 & 0 & 2 & -1 \\ 1 & 1 & 0 & 0 \end{array} \right] \Rightarrow \left[\begin{array}{ccc|c} 1 & 0 & \frac{2}{3} & -\frac{1}{3} \\ 1 & 1 & 0 & 0 \end{array} \right] \Rightarrow \left[\begin{array}{ccc|c} 1 & 0 & \frac{2}{3} & -\frac{1}{3} \\ 0 & 1 & -\frac{2}{3} & \frac{1}{3} \end{array} \right]$$

- Solve for z :

– Free variables: $\{x_3\}$. Let $x_3 = 1$.

– $x_2 - \frac{2}{3}(1) = \frac{1}{3} \Rightarrow x_2 = 1$

– $x_1 + \frac{2}{3}(1) = -\frac{1}{3} \Rightarrow x_1 = -1$

$\Rightarrow z = [-1 \ 1 \ 1]^T$

Example 3: $Ax = b$

- $\text{null}(A) = [-2 \ 2 \ 3]^T$
- Construct basis B :

$$\left\{ \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} -2 \\ 2 \\ 3 \end{bmatrix} \right\} = \begin{bmatrix} -1 & -3 \\ 1 & 3 \\ 1 & 4 \end{bmatrix}$$

$$\text{soln}(A, b) = B$$

Example 4: $Ax = b$

$$\begin{bmatrix} 3 & 0 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -1 \end{bmatrix}$$

- RREF:

$$\left[\begin{array}{ccc|c} 3 & 0 & 2 & -1 \end{array} \right] \Rightarrow \left[\begin{array}{ccc|c} 1 & 0 & \frac{2}{3} & -\frac{1}{3} \end{array} \right]$$

- Solve for z :

– Free variables: $\{x_2, x_3\}$. Let $x_2 = 1, x_3 = 1$.

– $x_1 + \frac{2}{3}(1) = -\frac{1}{3} \Rightarrow x_1 = -1$

$\Rightarrow z = [-1 \ 1 \ 1]^T$

Example 4: $Ax = 0$

- $\text{null}(A) = \begin{bmatrix} 0 & -2 \\ 1 & 0 \\ 0 & 3 \end{bmatrix}$

- Construct basis B :

$$\left\{ \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} -2 \\ 0 \\ 3 \end{bmatrix} \right\} = \begin{bmatrix} -1 & -1 & -3 \\ 1 & 2 & 1 \\ 1 & 1 & 4 \end{bmatrix}$$

$$\text{soln}(A, b) = B$$

Duality

Two representations of a linear space.

$$Ax = 0 \Leftrightarrow x \in \text{lin}(X)$$

- $Ax = 0$ is the **constraint representation**.
- X is the **vertex representation**.

Two representations of an affine space.

$$Ax = b \Leftrightarrow x \in \text{aff}(X)$$

- $Ax = b$ is the **constraint representation**.
- X is the **vertex representation**.

Duality: Changing Representation (Linear)

$$Ax = 0 \Rightarrow x \in \text{lin}(X)$$

$$X = \text{null}(A)$$

$$Ax = 0 \Leftarrow x \in \text{lin}(X)$$

Set up equation:

$$X^T \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} = 0$$

Then

$$A^T = \text{null}(X^T)$$

Duality: Changing Representation (Affine)

$$Ax = b \Rightarrow x \in \text{aff}(X)$$

Given constraint representation $Ax = b$ of affine space S .

Define

$$\text{c2v}(A, b) \stackrel{\text{def}}{=} \text{soln}(A, b)$$

Then $X = \text{c2v}(A, b)$ is a vertex representation of S .

Duality: Changing Representation (Affine)

$$Ax = b \Leftrightarrow x \in \text{aff}(X)$$

Given vertex representation X of S .

Set up equation:

$$\underbrace{\begin{bmatrix} & -1 \\ X^\top & \vdots \\ & -1 \end{bmatrix}}_C \begin{bmatrix} a_1 \\ \vdots \\ a_n \\ b \end{bmatrix} = 0$$

Then

$$\begin{bmatrix} A^\top \\ b^\top \end{bmatrix} = \text{null}(C)$$

Define $\text{v2c}(X)$ to return A, b .

Then for $A, b = \text{v2c}(X)$, $Ax = b$ is a constraint representation of S .

Basic Operations

Given: Two affine spaces S_1, S_2 .

Intersection

$$\begin{array}{l} S_1 : A_1 x = b_1 \\ S_2 : A_2 x = b_2 \end{array} \Rightarrow S_1 \cap S_2 : \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} x = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

$$x \in S_1 \cap S_2 \Leftrightarrow (x \in S_1 \wedge x \in S_2)$$

Union (Affine Hull)

$$\begin{array}{l} S_1 : X_1 \\ S_2 : X_2 \end{array} \Rightarrow S_1 \cup S_2 : X_1 \cup X_2 \quad (\text{i.e., } [X_1 \ X_2])$$

$$(x \in S_1 \vee x \in S_2) \Rightarrow x \in S_1 \cup S_2$$

Basic Operations

Containment

$$\begin{array}{l} S_1 : X \\ S_2 : Ax = b \end{array} \Rightarrow S_1 \subseteq S_2 : (\forall x \in X)[Ax = b]$$

$$S_1 \subseteq S_2 \text{ iff } x \in S_1 \Rightarrow x \in S_2.$$

Use to implement convergence check $\text{post}(\mu(\ell), \tau) \models \mu(m)$.

Transformation For transform $x_k = a^\top x + b$ and $S_1 : X$,

$$[[x_k = a^\top x + b]]S_1 = \{[x_1 \cdots x_{k-1} \quad a^\top x + b \quad x_{k+1} \cdots x_n]^\top : x \in X\}$$

Minimization Minimize representation.

$$S : Ax = b$$

$$\text{minc}(A, b) \stackrel{\text{def}}{=} \text{v2c}(\text{c2v}(A, b))$$

$$S : X$$

$$\text{minv}(X) \stackrel{\text{def}}{=} \text{c2v}(\text{v2c}(X))$$

Post: Assignment

Affine assignment:

$$\text{post}(S, x'_k = a^\top x + b \wedge \bigwedge_{i \neq k} x'_i = x_i) = [[x_k = a^\top x + b]]S$$

Non-affine assignment:

$$\text{post}(S, x'_k = ? \wedge \bigwedge_{i \neq k} x'_i = x_i) = [[x_k = 0]]S \cup [[x_k = 1]]S$$

Post: Guard

Affine guard:

$$\text{post}(S, a^T x = b \wedge \bar{x}' = \bar{x}) = S \cap (a^T x = b)$$

Non-affine guard:

$$\text{post}(S, ? \wedge \bar{x}' = \bar{x}) = S$$

Example

$$\langle \{i_1, i_2, k : \mathbb{R}\}, \{\ell_0\}, \ell_0, i_1 = i_2 = k = 0, \{\tau_1, \tau_2, \tau_3\} \rangle$$

$$\tau_1 : i'_1 = i_1 + 1 \wedge i'_2 = i_2 \wedge k' = k + 1$$

$$\tau_2 : i'_1 = i_1 \wedge i'_2 = i_2 + 1 \wedge k' = k + 1$$

Q	$\mu(\ell_0)$	$\text{post}(\mu(\ell_0), \tau_1)$	$\text{post}(\mu(\ell_1), \tau_2)$	
$\{\ell_0\}$	$i_1 = i_2 = k = 0$ $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$	$\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$	$\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$	(1)
$\{\ell_0\}$	$i_1 + i_2 = k$ $\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$	$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & 1 \\ 1 & 2 & 2 \end{bmatrix}$	$\begin{bmatrix} 0 & 1 & 0 \\ 1 & 1 & 2 \\ 1 & 2 & 2 \end{bmatrix}$	(2)
$\{\}$	$i_1 + i_2 = k$			(3)

Example: Comments

1. $\text{post}(\mu(\ell_0), \tau_1) \not\models \mu(\ell_0)$ (1 = 0 = 1 = 0? No.)
 $\text{post}(\mu(\ell_0), \tau_2) \not\models \mu(\ell_0)$ (0 = 1 = 1 = 0? No.)
 $\Rightarrow \mu(\ell_0) := \mu(\ell_0) \vee \text{post}(\mu(\ell_0), \tau_1) \vee \text{post}(\mu(\ell_0), \tau_2)$
2. $\text{post}(\mu(\ell_0), \tau_1) \models \mu(\ell_0)$ (plug columns into $i_1 + i_2 = k$)
 $\text{post}(\mu(\ell_0), \tau_2) \models \mu(\ell_0)$ (plug columns into $i_1 + i_2 = k$)
3. Convergence.