Lecture 20. The Kadison-Singer problem, part II

Our goal in this lecture is to prove the following theorem, which will complete the solution of the Kadison-Singer problem.

Theorem 1. For $A_i \succeq 0$, $Tr(A_i) \leq \alpha$, $\sum_{i=1}^m A_i = I$, the maximum root of the (real-rooted) polynomial

$$\chi(x) = \left(1 - \frac{\partial}{\partial z_m}\right) \dots \left(1 - \frac{\partial}{\partial z_1}\right) \left(\det\left(\sum_{i=1}^m z_i A_i\right)\right)\Big|_{z_i = x, \forall i}$$

is at most $(1 + \sqrt{\alpha})^2$.

Let's first introduce some notation. For a stable polynomial $Q(z_1, \ldots, z_m)$, the barrier function in direction j is

$$\phi_{Q}^{j}\left(z\right) = \frac{\partial}{\partial z_{j}}\left[\log\left(Q\left(z\right)\right)\right].$$

For $i, j \in [n]$, freeze z_k for $k \neq i, j$ and regard $\phi_Q^j(z)$ as a polynomial in z_i , for which we denote $\lambda_1, \ldots, \lambda_n$ the roots in z_i . Then we can write

$$\phi_Q^j(z) = \sum_{l=1}^n \frac{1}{z_j - \lambda_l}.$$

We first show the following lemma. Recall that z being above the roots of Q means that Q(z+t) > 0 for any $t \ge 0$. We follow a simplified proof from Terrence Tao's blog.

Lemma 2. For any stable polynomial Q, if z is above the roots of Q, then $\forall i, j \in [n], \phi_Q^j(z)$ is monotone decreasing and convex in z_i .

Proof. We can assume that Q is a monic polynomial. (The leading coefficient must be positive and hence we can do this by scaling.) Denote $\phi_Q^j(x_i, x_j)$ to be the polynomial on \mathbb{R}^2 where the other variables $(z_{\ell} : \ell \notin \{i, j\})$ are frozen in \mathbb{R} . We claim that for any positive integer k,

$$(-1)^k \frac{\partial^k}{\partial x_j^k} \phi_Q^i(x_i, x_j) \ge 0.$$

To see this, (1) when i = j, it is directly from the expression $\phi_Q^i(x_i) = \sum_{l=1}^n \frac{1}{x_i - \lambda_l}$. (2) when $i \neq j$, for any fixed x_i , regarding Q as a polynomial in x_j , we have real roots $\lambda_l(x_i)$ for $l \in [n]$. We can write

$$Q(x_i, x_j) = \prod_{l=1}^n \left(x_j - \lambda_l \left(x_i \right) \right).$$

Since $\phi_Q^i(x_i, x_j) = \frac{\partial}{\partial x_i} \log (Q(x_i, x_j))$, we have that

$$(-1)^{k} \frac{\partial^{k}}{\partial x_{j}^{k}} \phi_{Q}^{i}\left(x_{i}, x_{j}\right) = (-1)^{k} \frac{\partial}{\partial x_{i}} \frac{\partial^{k}}{\partial x_{j}^{k}} \log\left(Q(x_{i}, x_{j})\right) = (-1)^{k-1} \frac{1}{(k-1)!} \sum_{l=1}^{n} \frac{1}{\left(x_{j} - \lambda_{l}\left(x_{i}\right)\right)^{k}}$$

Note that $\lambda_l(x_i)$ is continuous in x_i . It is known that it is also differentiable as a *complex function* in x_i , except for points of measure 0 (we will accept this claim without proof). We next claim that $\lambda_l(x_i)$ is non-increasing. To see this, if it is increasing, at some point the derivative is positive, let's say at x'_i . Then for a complex z_i close to x'_i with $Im(z_i) > 0$, we have $Im(\lambda_l(z_i)) > 0$, and $Q(z_i, \lambda_l(z_i)) = 0$. It is impossible since $z_i, \lambda_l(z_i)$ are both on the upper half plane, contradicting the fact that Q is stable. Therefore, $\lambda_l(x_i)$ is non-increasing, and

$$(-1)^k \frac{\partial}{\partial x_i} \frac{\partial^k}{\partial x_j^k} \log \left(Q(x_i, x_j) \right) \ge 0.$$

Next we show the following lemma.

Lemma 3. If Q is stable and $z \in \mathbb{R}^n$ is above its roots, with $\phi_Q^i(z) < 1$, then z is above the roots of $(1 - \frac{\partial}{\partial z_i})Q$.

Proof. For any $t \ge 0$, we have $\phi_Q^i(t+z) < 1$ by monotonicity. $\phi_Q^i(z) < 1$ implies that $Q'_{z_i}(z)/Q(z) < 1$. Since Q(z) > 0, we have that $Q'_{z_i}(z) < Q(z)$, which means that

$$(1 - \frac{\partial}{\partial z_i})Q(z) > 0.$$

Lemma 4. If Q is stable, z is above its roots, with $\phi_Q^i(z) \leq 1 - \frac{1}{\delta}$ for $\delta > 1$. Then

$$\phi_{\left(1-\frac{\partial}{\partial z_{j}}\right)Q}^{i}\left(z+\delta e_{j}\right) \leq \phi_{Q}^{i}\left(z\right).$$

Proof. We have that

$$\phi_{(1-\frac{\partial}{\partial z_j})Q}^i = \frac{\frac{\partial}{\partial z_i}(Q-Q'_{z_j})}{Q-Q'_{z_j}} = \frac{\partial_i Q}{Q} + \frac{\partial_i \left(1-\phi_Q^j\right)}{1-\phi_Q^j} = \phi_Q^i - \frac{\partial_j \phi_Q^i}{1-\phi_Q^j},\tag{1}$$

where we write ∂_i for $\frac{\partial}{\partial z_i}$ for short. Note that

$$\partial_{j}\phi_{Q}^{i}\left(z+\delta\right) \geq \partial_{j}\phi_{Q}^{i}\left(z_{j}\right) \geq \frac{\phi_{Q}^{i}\left(z_{j}+\delta\right)-\phi_{Q}^{i}\left(z_{j}\right)}{\delta}$$

By (1) we have that

$$\phi^{i}_{(1-\frac{\partial}{\partial z_{j}})Q}(z_{j}+\delta) = \phi^{i}_{Q}(z_{j}+\delta) - \frac{\partial_{j}\phi^{i}_{Q}(z_{j}+\delta)}{1-\phi^{j}_{Q}(z_{j}+\delta)}.$$
(2)

By our condition we have that

$$1 - \phi_Q^j \left(z_j + \delta \right) \ge 1 - \phi_Q^j \left(z_j \right) \ge \frac{1}{\delta},$$

and thus

$$\frac{\partial_j \phi_Q^i(z_j + \delta)}{1 - \phi_Q^j(z_j + \delta)} \ge \delta \partial_j \phi_Q^i(z_j + \delta) \ge \phi_Q^i(z_j + \delta) - \phi_Q^i(z_j).$$
(3)

Substituting (3) into (2) we see that

$$\phi^{i}_{(1-\frac{\partial}{\partial z_{j}})Q}\left(z_{j}+\delta\right) \leq \phi^{i}_{Q}\left(z_{j}\right).$$

Now we are ready to prove Theorem 1.

Proof of Theorem 1 Let

$$Q_k(z_1, \ldots, z_m) = \left(1 - \frac{\partial}{\partial z_k}\right) \ldots \left(1 - \frac{\partial}{\partial z_1}\right) \left[\det\left(\sum_{i=1}^m z_i A_i\right)\right].$$

We claim that barrier functions are bounded by $1 - \frac{1}{\delta}$ for $\delta = 1 + \sqrt{\alpha}$, if with each $\left(1 - \frac{\partial}{\partial z_k}\right)$

operation, we increase t in the respective coordinate by δ . We use induction to show this. In the base case we have that

$$Q_0(z_1,\ldots,z_m) = \det\left(\sum_{i=1}^m z_i A_i\right),$$

and thus

$$Q_0(t,\ldots,t) = \det\left(\sum_{i=1}^m tA_i\right) = t^n > 0.$$

Recall that

$$\frac{d}{dt} \left(\det \left(A + tB \right) \right)|_{t=0} = \det \left(A \right) Tr \left(A^{-1}B \right).$$

Using the above identity we see that

$$\phi_{Q_0}^i\left(z_1,\ldots,z_m\right) = Tr\left(\left(\sum_{i=1}^m z_i A_i\right)^{-1} A_i\right),\,$$

which implies that

$$\phi_{Q_0}^i(t,\ldots,t) = \frac{1}{t} Tr(A_i) \le \alpha/t,$$

since we assumed that $Tr(A_i) < \alpha$. Letting $t = \alpha + \sqrt{\alpha}$, we further see that

$$\phi_{Q_0}^i(t,\ldots,t) \le 1 - \frac{1}{1+\sqrt{\alpha}} = 1 - \frac{1}{\delta}.$$

Now assume that the claim holds for k. We have that

$$\begin{split} \phi^{i}_{Q_{k+1}} \left(\underbrace{t + \delta, \dots, t + \delta}_{k+1}, t, \dots, t \right) \\ &= \phi^{i}_{(1 - \partial_{k+1})Q_{k}} \left(\underbrace{t + \delta, \dots, t + \delta}_{k+1}, t, \dots, t \right) \\ &\leq \phi^{i}_{Q_{k}} \left(\underbrace{t + \delta, \dots, t + \delta}_{k}, t, \dots, t \right) \\ &\leq 1 - \frac{1}{\delta}. \end{split}$$

Therefore we see that $\chi(x) = Q_m(x, ..., x)$ has maximum root at most $t + \delta = (1 + \sqrt{\alpha})^2$.